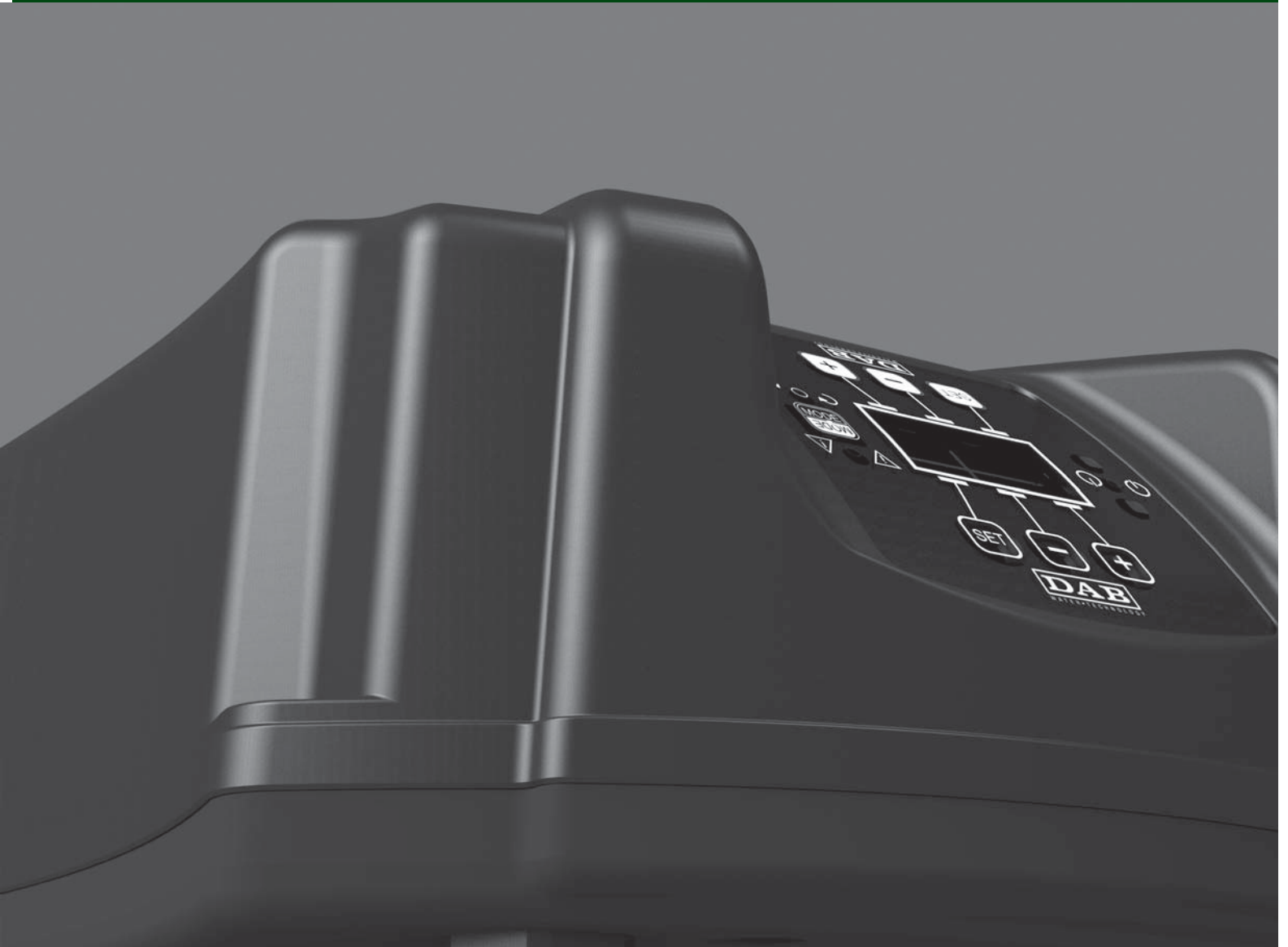


INVERTER MCE/P

MCE/P 11-MCE/P 15-MCE/P 22
MCE/P 30-MCE/P 55
MCE/P 110-MCE/P 150





Description

The MCE/P is the leading edge of the Dab inverters. The 3 models of this family are ideal for professional and very severe applications. They can drive pumps of up to 15 kW. These units combine the simplicity of the MCE/P series with the robust design and power of an inverter drive. These devices are mounted on the pump, and are equipped with pressure sensors and the optional flow sensors as required. The use of a flow sensor, moreover, allows a better pressure regulation. The MCE/P can easily be set up in booster sets, thanks to a standard wire cable connection. Comfort, energy saving, protections and simplicity are the keywords of this professional series.

Benefits

Why the Dab inverter?

The MCE/P units are air cooled. These extremely robust panel-mounting inverters feature a metal body and are suitable for heavy-duty applications. Operation of these inverters calls for the presence of a pressure sensor and, optionally, a flow sensor. MCE/P combines practicality with easy installation and management. MCE/P ensure the utmost practicality and increase the average working life of the system, permitting also significant savings in power consumption.

Advantages

- Easily installed in existing systems
- Constant pressure
- Power consumption reduced by up to 60%
- Built-in protections
- Operates with all pumps
- Robust
- Facility to create sets with interchange of up to 8 pumps
- IP55 protection rating



Characteristics

MCE/P 11 – MCE/P 15 – MCE/P 22

- Self-ventilated panel-mounting inverters for hydraulic pumps.
- For three-phase pumps up to 3 HP - 2.2 kW
- OLED graphic display
- Input power supply 1 x 230V 50-60Hz
- Pump voltage 3 x 230V
- Electric pump nominal frequency 50-200 Hz
- Control range in accordance with the sensor utilised, with standard range of 1-24bar
- Protections against voltage surges
- Adjustable overload protection
- Built-in flow sensor (Optional)
- Extended connectivity
- Protection rating: IP55
- Dry run protection
- Short circuit between output phases
- Overtemperature protection
- Anti-seize and anti-frost function
- Facility to create booster sets with up to 8 inverters

MCE/P 30 – MCE/P 55

- Self-ventilated panel-mounting inverters for hydraulic pumps.
- For three-phase pumps up to 7.5 HP - 5.5 kW
- OLED graphic display
- Input power supply 3 x 400V 50-60Hz
- Pump voltage 3 x 400V
- Electric pump nominal frequency 50-200 Hz
- Control range in accordance with the sensor utilised, with standard range of 1-24bar
- Protections against voltage surges
- Adjustable overload protection
- Built-in flow sensor
- Extended connectivity
- Protection rating: IP55
- Dry run protection
- Short circuit between output phases
- Overtemperature protection
- Anti-seize and anti-frost function
- Facility to create booster sets with up to 8 inverters

MCE/P 110 – MCE/P 150

- Self-ventilated panel-mounting inverters for hydraulic pumps.
- For three-phase pumps up to 20HP – 15kW
- OLED graphic display
- Input power supply 3 x 400V 50-60Hz
- Pump voltage 3 x 400V
- Electric pump nominal frequency 50-200 Hz
- Control range in accordance with the sensor utilised, with standard range of 1-24bar
- Protections against voltage surges
- Adjustable overload protection
- Built-in flow sensor
- Extended connectivity
- Protection rating: ip55
- Dry run protection
- Short circuit between output phases
- Overtemperature protection
- Anti-seize and anti-frost function
- Facility to create booster sets with up to 8 inverters

| Model | Max. motor current A | Max. motor power kW | Power supply V | Pump Input V | Parallel user interface | Maximum dimensions L x H x P |
|-----------------|-------------------------|------------------------|---------------------|----------------------|-------------------------|---------------------------------|
| MCE/P 11 | 6.5 | 1.5 | Mono-phase 1x230 | Three-phase 3x230 | YES | 200 x 199 x 262 |
| MCE/P 15 | 8,0 | 2 | Mono-phase 1x230 | Three-phase 3x230 | YES | 200 x 199 x 262 |
| MCE/P 22 | 10.5 | 2.8 | Mono-phase 1x230 | Three-phase 3x230 | YES | 200 x 199 x 262 |

| | | MCE/P 11 | MCE/P 15 | MCE/P 22 |
|---|---|------------------------------------|---------------|----------|
| Inverter power feeding | Voltage [VAC] (Tolerance +10/-20%) | 220-240 | | |
| | Phases | 1 | | |
| | Frequency [Hz] | 50 - 60 Hz | | |
| | Current [A] | 12 | 18,7 | 22 |
| Inverter power output | Voltage [VAC] (Tolerance +10/-20%) | 0 - V power supply | | |
| | Phases | 3 | | |
| | Frequency [Hz] | 0-200 | | |
| | Current [A] | 6,5 | 8 | 10.5 |
| | Max electrical power output [kVA] (400 Vrms) | 1,5 | 2 | 2.8 |
| Mechanical power rating P2 | 1,5 CV / 1,1 kW | 2 CV / 1,5 Kw | 3 CV / 2,2 kW | |
| Mechanical characteristics | Unit weight [kg] (packing included) | 5.0 | | |
| | Maximum dimensions [mm] (WxHxD) | 200x199x262 | | |
| Installation | Operating position | Any position | | |
| | IP protection rating | 55 | | |
| | Maximum ambient temperature [°C] | 40 | | |
| | Maximum conductor section accepted by input and output terminals [mm ²] | 4 | | |
| | Minimum cable diameter accepted by inlet and outlet cable glands [mm] | 6 | | |
| Maximum cable diameter accepted by inlet and outlet cable glands [mm] | 12 | | | |
| Control and operation hydraulic characteristics | Pressure control range [bar] | 1 – 95% pressure sensor full scale | | |
| | Options | Flow sensor | | |

| | | MCE/P 11 | MCE/P 15 | MCE/P 22 |
|---------------------------|-----------------------------------|---|----------|----------|
| Sensors | Types of pressure sensor | Ratiometric sensor - 4:20 mA | | |
| | Pressure sensors full scale [bar] | 16 / 25 / 40 | | |
| | Type of flow sensor supported | Pulses 5 [Vpp] | | |
| Functions and protections | Connectivity | Serial interface - Multi inverter connection | | |
| | Protections | - Dry-run - Overload protection on output phases - Internal electronics temperature protection - Anomalous power supply voltages - Direct short circuit between output phases - Pressure sensor fault | | |

TECHNICAL DATA



MCE/P 30 – MCE/P 55

| Model | Max. motor current A | Max. motor power kW | Power supply V | Pump Input V | Parallel user interface | Maximum dimensions L x H x P |
|-----------------|-------------------------|------------------------|----------------------|----------------------|-------------------------|---------------------------------|
| MCE/P 30 | 7,5 | 3 | Three-phase 3x400 | Three-phase 3x400 | YES | 267 x 196 x 352 |
| MCE/P 55 | 13,5 | 5,5 | Three-phase 3x400 | Three-phase 3x400 | YES | 267 x 196 x 352 |

| | | MCE/P 30 | MCE/P 55 |
|---|---|------------------------------------|-------------|
| Inverter power feeding | Voltage [VAC] (Tolerance +10/-20%) | 380-480 | |
| | Phases | 3 | |
| | Frequency [Hz] | 50 - 60 Hz | |
| | Current [A] | 11,5 - 9,0 | 17,0 - 13,0 |
| Inverter power output | Voltage [VAC] (Tolerance +10/-20%) | 0 - V power supply | |
| | Phases | 3 | |
| | Frequency [Hz] | 0-200 | |
| | Current [A] | 7,5 | 13,5 |
| | Max electrical power output [kVA] (400 Vrms) | 4,0 | 7,0 |
| Mechanical power rating P2 | 4 CV/3.0 Kw | 7,5 CV / 5,5 kW | |
| Mechanical characteristics | Unit weight [kg] (packing included) | 7,6 | |
| | Maximum dimensions [mm] (WxHxD) | 267 x 196 x 352 | |
| Installation | Operating position | Any position | |
| | IP protection rating | 55 | |
| | Maximum ambient temperature [°C] | 40 | |
| | Maximum conductor section accepted by input and output terminals [mm ²] | 4 | |
| | Minimum cable diameter accepted by inlet and outlet cable glands [mm] | 11 | |
| | Maximum cable diameter accepted by inlet and outlet cable glands [mm] | 17 | |
| Control and operation hydraulic characteristics | Pressure control range [bar] | 1 – 95% pressure sensor full scale | |
| | Options | Flow sensor | |

| | | MCE/P 30 | MCE/P 55 |
|---------------------------|-----------------------------------|---|----------|
| Sensors | Types of pressure sensor | Ratiometric sensor - 4:20 mA | |
| | Pressure sensors full scale [bar] | 16 / 25 / 40 | |
| | Type of flow sensor supported | Pulses 5 [Vpp] | |
| Functions and protections | Connectivity | Serial interface - Multi inverter connection | |
| | Protections | - Dry-run - Overload protection on output phases - Internal electronics temperature protection - Anomalous power supply voltages - Direct short circuit between output phases - Pressure sensor fault | |

| Model | Max. motor current A | Max. motor power kW | Power supply V | Pump Input V | Parallel user interface | Maximum dimensions L x H x P |
|------------------|-------------------------|------------------------|----------------------|----------------------|-------------------------|---------------------------------|
| MPE/P 110 | 24 | 14,0 | Three-phase 3x400 | Three-phase 3x400 | YES | 343 x 244 x 425 |
| MPE/P 150 | 32 | 19,0 | Three-phase 3x400 | Three-phase 3x400 | YES | 343 x 244 x 425 |

| | | MPE/P 110 | MPE/P 150 |
|---|---|---------------------------------------|---------------|
| Inverter power feeding | Voltage [VAC] (Tolerance +10/-20%) | 380-480 | |
| | Phases | 3 | |
| | Frequency [Hz] | 50 - 60 Hz | |
| | Current [A] | 32,5-26,0 | 42,0-33,5 |
| Inverter power output | Voltage [VAC] (Tolerance +10/-20%) | 0 - V alim. | |
| | Phases | 3 | |
| | Frequency [Hz] | 0-200 | |
| | Current [A] | 24,0 | 32,0 |
| | Max electrical power output [kVA] (400 Vrms) | 14,0 | 19,0 |
| | Mechanical power rating P2 | 15 CV / 11 kW | 20 CV / 15 kW |
| Mechanical characteristics | Unit weight [kg] (packing included) | 12,0 | |
| | Maximum dimensions [mm] (WxHxD) | 343 x 244 x 425 | |
| Installation | Operating position | Any position | |
| | IP protection rating | 55 | |
| | Maximum ambient temperature [°C] | 40 | |
| | Maximum conductor section accepted by input and output terminals [mm ²] | 4 | |
| | Minimum cable diameter accepted by inlet and outlet cable glands [mm] | 11 | |
| | Maximum cable diameter accepted by inlet and outlet cable glands [mm] | 17 | |
| Control and operation hydraulic characteristics | Pressure control range [bar] | 1 – 95% pressure sensor full scale | |
| | Options | Flow sensor Redundant pressure sensor | |

| | | MPE/P 110 | MPE/P 150 |
|---------------------------|-----------------------------------|---|-----------|
| Sensors | Types of pressure sensor | Ratiometric sensor - 4:20 mA | |
| | Pressure sensors full scale [bar] | 16 / 25 / 40 | |
| | Type of flow sensor supported | Pulses 5 [Vpp] | |
| Functions and protections | Connectivity | Serial interface - Multi inverter connection | |
| | Protections | - Dry-run - Overload protection on output phases - Internal electronics temperature protection - Anomalous power supply voltages - Direct short circuit between output phases - Pressure sensor fault | |

Reducing motor speed, even marginally, can lead to an appreciable reduction in power consumption because the absorbed power of an electric motor is proportional to the rpm cubed. For example, a pump powered by the mains that runs at approximately 2950 rpm, will run approximately 20% slower (i.e. at 2360 rpm) when fed with a 40 Hz supply, leading to a saving of 40% in terms of absorbed power.

The motor speed reduction increases pump life significantly, thanks to the reduction of mechanical stress.

Pump performance in relation to variations in rpm

Pump rpm n has a very significant influence on pump performance.

In the absence of cavitation phenomena the law of similarity is applicable, as shown in equation 1.

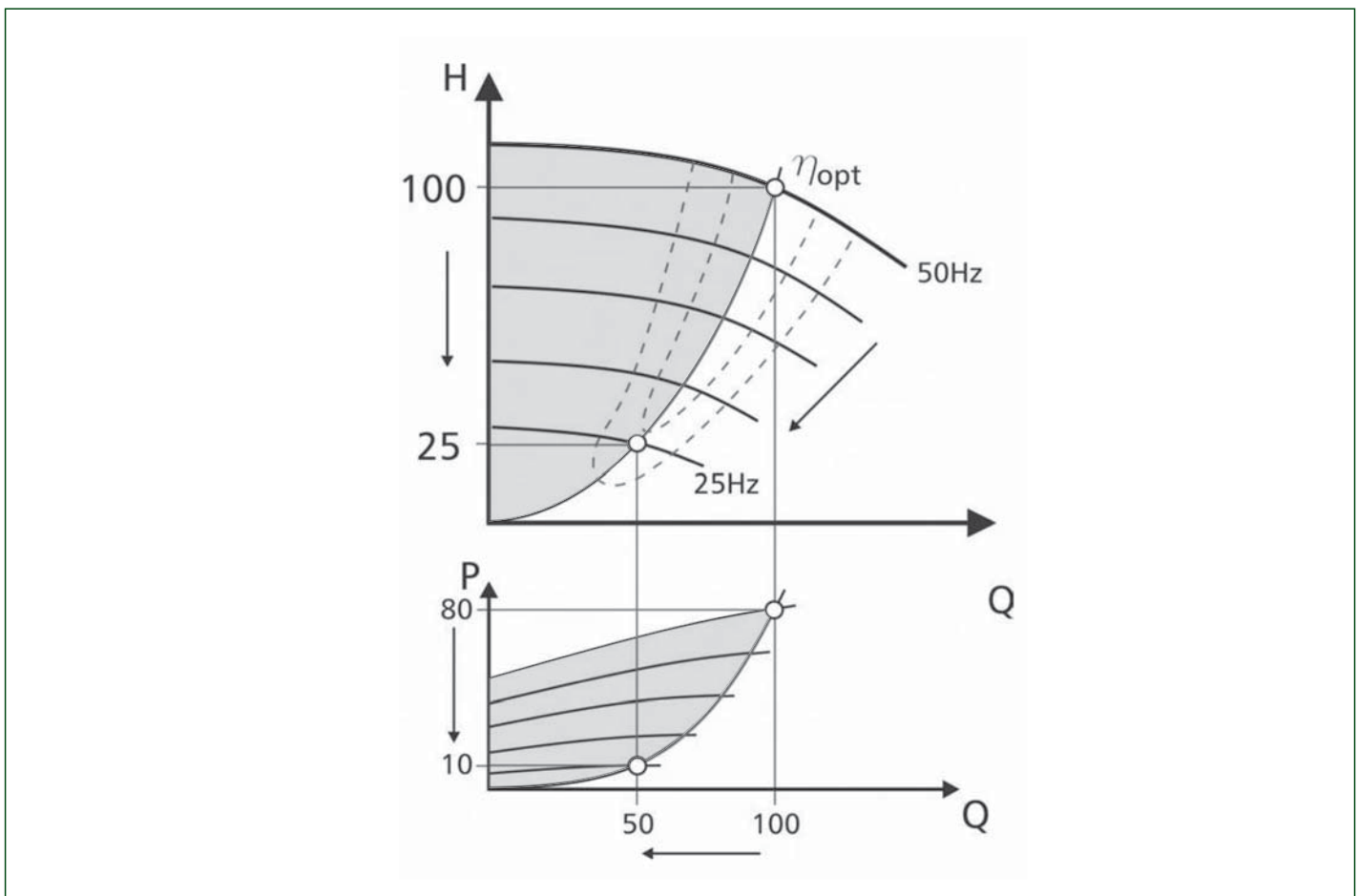
- Flow rate changes in a linear manner with changes in speed.
- Pressure changes in a squared relationship with changes in rpm.
- Power changes in a cubed relationship with changes in rpm.
- A small change in rpm produces a very large change in power.

Equation 1

$$\frac{Q_x}{Q} = \frac{n_x}{n} \quad Q = Q_x \frac{n_x}{n}$$

$$\frac{H_x}{H} = \left(\frac{n_x}{n}\right)^2 \quad H_x = H \left(\frac{n_x}{n}\right)^2$$

$$\frac{P_x}{P} = \left(\frac{n_x}{n}\right)^3 \quad P_x = P \left(\frac{n_x}{n}\right)^3$$



- a lowering of the flow acc. to the linear function
- a reduction of the head according to a quadratic function
- a reduction of the power consumption acc. to a cubic function!

MCE/P 11 – MCE/P 15 – MCE/P 22

Example showing use of a 2,2 kW pump for 10 hours/day *

| Performance required of the pump | Minutes/day | Instantaneous power (ON/OFF) | Power with PWM | kWh (ON/OFF) | kWh (INVERTER) | kWh saved |
|----------------------------------|-------------|------------------------------|----------------|--------------|----------------|-------------|
| 0% - 20% | 30 | 1,32 | 0,50 | 0,66 | 0,25 | 0,41 |
| 20% - 30% | 30 | 1,32 | 0,50 | 0,66 | 0,25 | 0,41 |
| 30% - 40% | 60 | 1,37 | 0,55 | 1,37 | 0,55 | 0,82 |
| 40% - 50% | 240 | 1,41 | 0,60 | 5,66 | 2,39 | 3,27 |
| 50% - 60% | 120 | 1,54 | 0,69 | 3,08 | 1,38 | 1,70 |
| 60% - 70% | 54 | 1,82 | 0,94 | 1,64 | 0,85 | 0,79 |
| 70% - 80% | 30 | 2,04 | 1,30 | 1,02 | 0,65 | 0,37 |
| 80% - 90% | 24 | 2,17 | 1,76 | 0,87 | 0,70 | 0,16 |
| 90% - 100% | 12 | 2,20 | 2,07 | 0,44 | 0,41 | 0,03 |
| | | | TOT. | 15,39 | 7,44 | 7,95 |

YEARLY SAVING

7,95 kWh X 365 = 2902 kWh / 2902 kWh X 0,2 € / kWh = **€ 580,34**

As we will see, in an average day of operation the MCE/P unit provides a saving of 7,95 kWh, equivalent to 60%, with respect to the consumption of a conventional on/off pump.

MCE/P 30 – MCE/P 55

Example showing use of a 5,5 kW pump for 10 hours/day *

| Performance required of the pump | Minutes/day | Instantaneous power (ON/OFF) | Power with PWM | kWh (ON/OFF) | kWh (INVERTER) | kWh saved |
|----------------------------------|-------------|------------------------------|----------------|--------------|----------------|--------------|
| 0% - 20% | 30 | 3,30 | 1,26 | 1,65 | 0,63 | 1,02 |
| 20% - 30% | 30 | 3,30 | 1,26 | 1,65 | 0,63 | 1,02 |
| 30% - 40% | 60 | 3,42 | 1,38 | 3,42 | 1,38 | 2,04 |
| 40% - 50% | 240 | 3,54 | 1,49 | 14,14 | 5,97 | 8,17 |
| 50% - 60% | 120 | 3,85 | 1,73 | 7,70 | 3,46 | 4,24 |
| 60% - 70% | 54 | 4,56 | 2,36 | 4,10 | 2,12 | 1,98 |
| 70% - 80% | 30 | 5,11 | 3,26 | 2,55 | 1,63 | 0,92 |
| 80% - 90% | 24 | 5,42 | 4,40 | 2,17 | 1,76 | 0,41 |
| 90% - 100% | 12 | 5,50 | 5,19 | 1,10 | 1,04 | 0,06 |
| | | | TOT. | 38,48 | 18,61 | 19,87 |

YEARLY SAVING

19,87 kWh X 365 = 7254 kWh
7254 kWh X 0,2 € / kWh =
€ 1.450,85

As we will see, in an average day of operation the MCE/P unit provides a saving of 19,87 kWh, equivalent to 60%, with respect to the consumption of a conventional on/off pump.

MCE/P 110 – MCE/P 150

Example showing use of a 15 kW pump for 10 hours/day *

| Performance required of the pump | Minutes/day | Instantaneous power (ON/OFF) | Power with PWM | kWh (ON/OFF) | kWh (INVERTER) | kWh saved |
|----------------------------------|-------------|------------------------------|----------------|---------------|----------------|--------------|
| 0% - 20% | 30 | 9,00 | 3,43 | 4,50 | 1,71 | 2,79 |
| 20% - 30% | 30 | 9,00 | 3,43 | 4,50 | 1,71 | 2,79 |
| 30% - 40% | 60 | 9,32 | 3,75 | 9,32 | 3,75 | 5,57 |
| 40% - 50% | 240 | 9,64 | 4,07 | 38,57 | 16,29 | 22,29 |
| 50% - 60% | 120 | 10,50 | 4,71 | 21,00 | 9,43 | 11,57 |
| 60% - 70% | 54 | 12,43 | 6,43 | 11,19 | 5,79 | 5,40 |
| 70% - 80% | 30 | 13,93 | 8,89 | 6,96 | 4,45 | 2,52 |
| 80% - 90% | 24 | 14,79 | 12,00 | 5,91 | 4,80 | 1,11 |
| 90% - 100% | 12 | 15,00 | 14,14 | 3,00 | 2,83 | 0,17 |
| | | | TOT. | 104,96 | 50,75 | 54,20 |

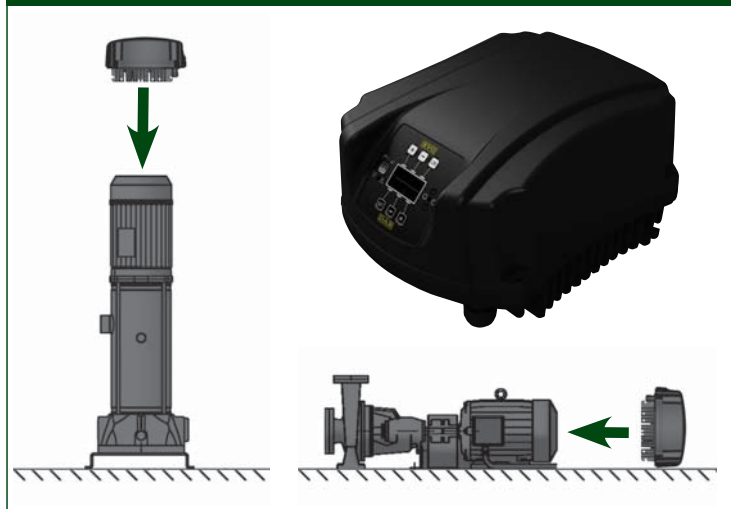
YEARLY SAVING

54,20 kWh X 365 = 19784 kWh
19784 kWh X 0,2 € / kWh =
€ 3.956,86

As we will see, in an average day of operation the MCE/P unit provides a saving of 54,20 kWh, equivalent to 60%, with respect to the consumption of a conventional on/off pump.

*The table shows a comparison of **daily consumption** of a standard pump driven by an On/Off system and a pump driven by a MCE/P inverter.

1 Connections on motor



The MCE is installed on the motor base. The inverter can operate both vertically and horizontally. 2 kits are available for assembly on the motor:

Tie-rods:

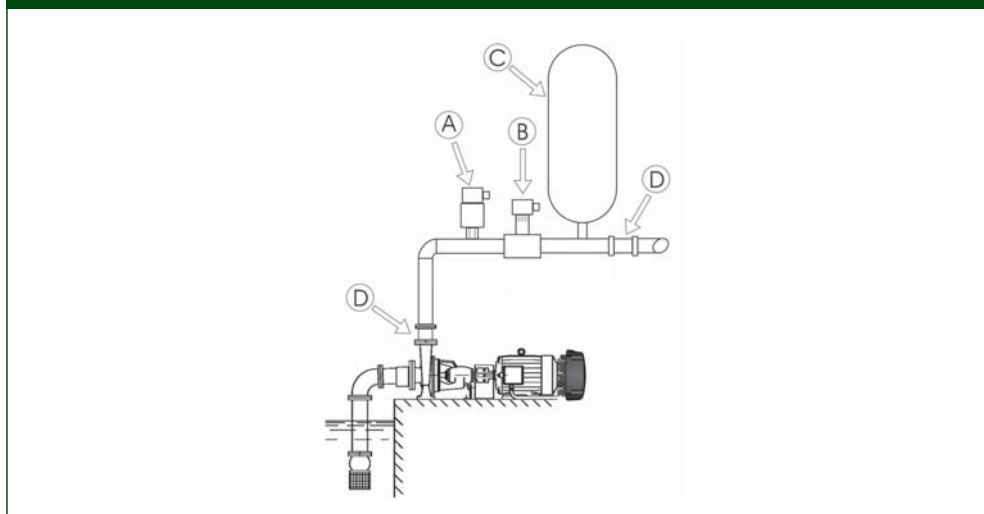
These are connected to the MCE dissipator and fan cover. They require a solid fan cover able to withstand the weight of the inverter, i.e. secured by means of bolts or screws.

Fan cover kit:

The fan cover kit is used in all situations where the fan cover is not sufficiently solid or strong enough to withstand the weight of the inverter.

HYDRAULIC CONNECTION

1 Hydraulic diagram



Parts that make up the system

| | |
|---|-----------------|
| A | Pressure sensor |
| B | Flow sensor |
| C | Gun barrel |
| D | Check Valve |

The Picture 1 shows the scheme of a correct Hydraulic installation.

The MCE/P is a panel inverter and is connected to the hydraulic section by means of pressure and flow sensors. The pressure sensor is always required, while the flow sensor is optional.

Both are mounted on pump delivery and connected by means of the relative cables to the respective inputs on the MCE/P board.

Always fit a check valve on pump suction and an expansion vessel on pump delivery. In all circuits subject to the risk of water hammer (for example irrigation systems with flow rate interrupted suddenly by solenoid valves), fit a further check valve downline of the pump and mount the sensors and expansion vessel between the pump and valve.

The hydraulic connection between the pump and sensors must not have branched sections.

Pipelines must be sized according to the type of electric pump installed. Excessively deformable systems may generate oscillations; if this occurs, the user may solve the problem by adjusting control parameters "GP" and "GI".

Note: The MCE/P system works at constant pressure. This setting is best exploited if the hydraulic system downline of the system is suitably sized. Systems with excessively small pipelines can cause pressure drops for which the equipment is unable to compensate; the result is constant pressure on the sensors but not on the utility.



Foreign bodies in the pipeline: the presence of dirt in the fluid may obstruct transfer channels, block the flow or pressure sensor and impair correct system operation.

Take care to install the sensors so that they are not subject to the build-up of excessive sediment or air bubbles that may impair operation. If the size of the pipeline enables transit of foreign bodies, a special filter may need to be installed.

Connection to the power line

The connection between the power line and MCE/P must be made using a 3-wire cable (2 phases + earth) or 4-wire cable (3 phases + earth) depending on the model of inverter.

The input terminals are those marked LN and an arrow pointing towards the terminals (figure A, page 10)

The section, type and laying of cables for inverter power supply and electric pump connections must be selected in compliance with current standards. Table 2: Cable sections provides indications on the cable section to be used. The table refers to cables in PVC with 4 wires (3 phases + earth) with the minimum recommended section based on the current and length of cable.

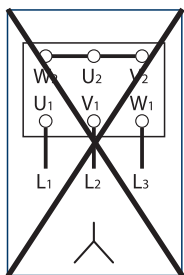
The electric pump current is normally specified on the motor dataplate. The current supply to the MCE/P can normally be calculated (taking a safety margin into account) as 1/3 of the current absorbed by the pump. Although the MCE/P is already equipped with internal safety devices, the installation of a suitably sized thermal magnetic circuit breaker is recommended. If the entire power range available is used, for specific information on the current to be used when choosing cables and the thermal magnetic circuit breaker.

! The thermal magnetic circuit breaker and power cables of the MCE/P and pump must be sized according to the system; if the specifications in the manual do not correspond to provisions of current standards, use only the latter as a reference.

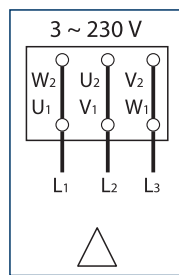


Connwction to pump (only for series MCE/P 11 – MCE/P 15 – MCE/P 22)

The power supply voltage of the installed electric pump must be 230 V three-phase. Three-phase electrical machinery generally has 2 types of connection, as shown in Figure 3 and Figure 4



3 Incorrect connection



4 Correct connection

The delta connection is the one typically used for working at 230 V (lower voltage).

For versions not supplied with the cable, the connection is on the 4-way

terminal marked "PUMP" and with the arrow on output. The minimum cable section must be 1.5 mm².

! Incorrect connection of the earth lines to a terminal other than the earth terminal may cause irremediable damage to the whole appliance!

Incorrect connection of the power supply line on output terminals intended for the load may cause irremediable damage to the whole appliance!

Connection of sensors

The terminations for sensor connections are on the lower right section and are accessible by removing the screw of the connections cover. Cover removal for access to connections. The sensors must be connected to the relative inputs marked "Press" and "Flow".

Connecting the flow sensor (Optional)

The flow sensor is supplied with its own cable. One end of the cable must be connected to the sensor and the other end to the relative inverter flow sensor input, marked "Flow 1"; see Figure 2 pag. 9: Connections.

The cable has two different terminals with compulsory direction of insertion: connector for industrial applications (DIN 43650) on the sensor side and 6-pole connector on the MCE/P side.

Note: the flow sensor and pressure sensor are both fitted with a DIN 43650 type connector, and therefore take care to ensure the correct sensor is connected to the correct cable.

Connecting a ratiometric sensor

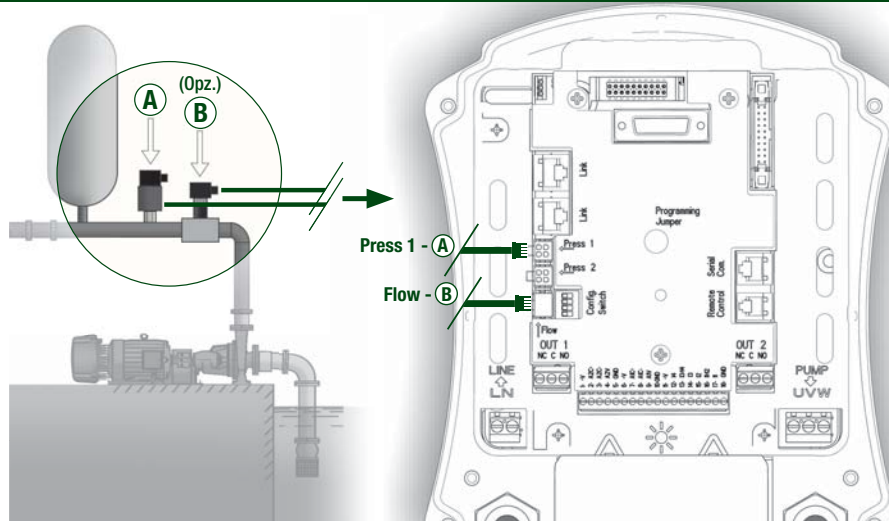
One end of the cable must be connected to the sensor and the other end to the relative inverter pressure sensor input, marked "Press 1".

The cable has two different terminals with compulsory direction of insertion: connector for industrial applications (DIN 43650) on the sensor side and 4-pole connector on the MCE/P side.

2 Sensors connection

MCE/P 11 – MCE/P 15 – MCE/P 22

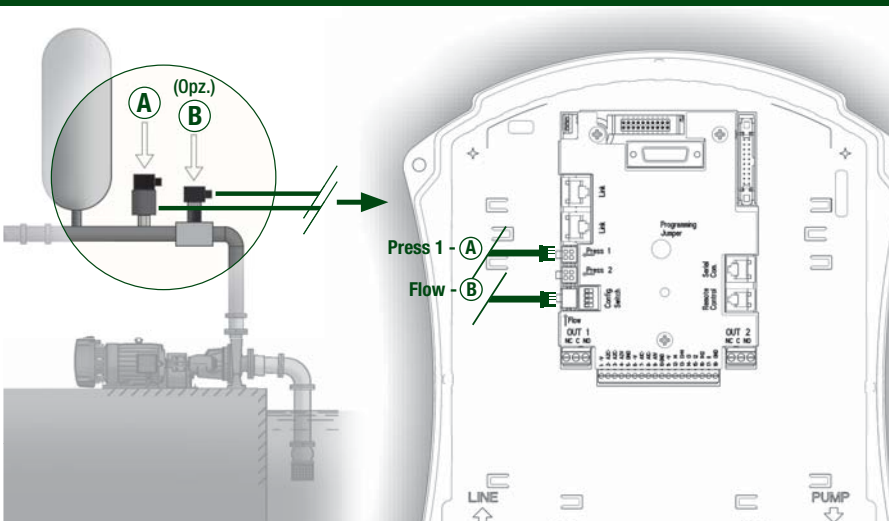
- A PRESSURE SENSOR (REQUIRED)
- B FLOW SENSOR (OPTIONAL)



2 Sensors connection

MCE/P 30 – MCE/P 55

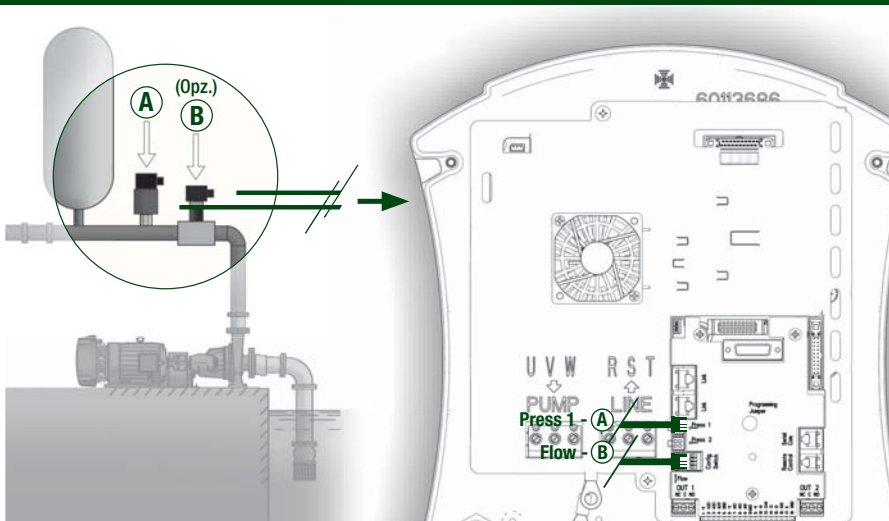
- A PRESSURE SENSOR (REQUIRED)
- B FLOW SENSOR (OPTIONAL)



2 Sensors connection

MCE/P 110 – MCE/P 150

- A PRESSURE SENSOR (REQUIRED)
- B FLOW SENSOR (OPTIONAL)



The MCE/P series of inverters can identify flow in accordance with three different methods:

- By means of the flow sensor
- Self-adaptive mode (without Flow Sensor)
- Manual mode (without Flow Sensor)

By means of the flow sensor:

The flow is detected by a flow sensor; this maximises performance and efficiency. The flow is read directly by the flow sensor, so that the system responds in reliable times to any variation of conditions that occurs in the system.

For example: in the absence of water, the system will stop the pump precisely within the time set in parameter *tb* (trip time).

To set this algorithm correctly, set the type of sensor utilised, parameter *FI*, and the diameter of the piping, parameter *FD*

Self-Adaptive Mode (Without Flow Sensor)

This mode is composed of the use of a specific and highly effective self-adaptive algorithm.

The algorithm acquires information and updates its parameters during operation. To achieve optimal operation ensure that the hydraulic installation is not subject to modifications that result in a significant variation in its characteristics (such as, for example, solenoid valves that switch between hydraulic sectors with very different characteristics) during normal operation, because the algorithm will set up to match one of the conditions and may not give the required results when the changeover occurs. In contrast, no problems exist if the installation characteristics are substantially unchanged (length, elasticity and required minimum flow rate). There is also no problem if the inverter is restarted after the installation has been modified. This is because the acquired values are reset every time the system is restarted or reset.


The adaptation procedure takes up to 3-4 hours, and during this period the algorithm will switch off the inverter to attempt to read the hydraulic flow rate. The operation can be speeded up by using the fast teach-in method for self-adaptive mode (refer to the manual)


The algorithm utilised measures various significant parameters and analyses the unit status to detect the presence and magnitude of the flow. For this reason, and to avoid nuisance tripping, it is important to set up the parameters correctly; specifically, perform correct set-up of rated current *RC*; set adequate minimum flow *FT*, set correct minimum frequency *FL*, and set the correct direction of run.

Manual Mode

This completely manual mode makes it possible to set the frequency (*FZ*) below which flow is considered to be zero.

This means the pump will stop when the rotation frequency drops below *FZ* for the time set in parameter *T2* (trip time for zero flow).

 If *FZ* is too high, the pump may switch off even in the presence of a flow, and then switch on again as soon as the pressure falls below the restart pressure. This may lead to repeated stops and starts also in rapid succession.

 If *FZ* is too low, the pump may never switch off even in the absence of a flow or with very low flow rates. This situation may lead to damage of the pump due to overheating.

NOTE: Manual mode is the only mode available for pressure units without flow sensor.

FZ shutdown frequency settings:

Open the utility and check the operating frequency of the inverter. Reduce the flow by closing the utilities until the minimum flow rate for inverter shutdown is reached.

Note this parameter and set *FZ* at this value +2Hz.

 Changes to the set point require repetition of the entire procedure.

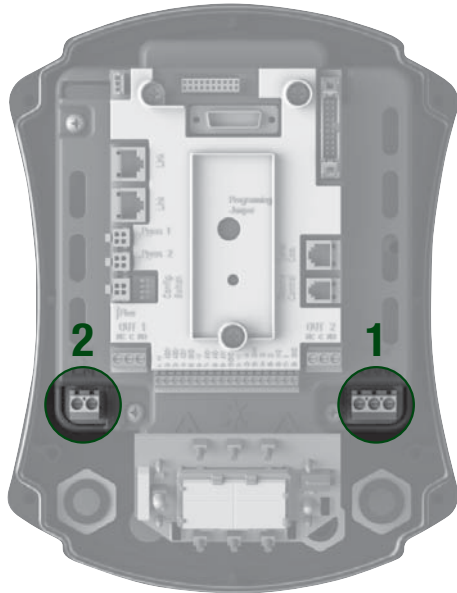
QUICK START GUIDE

PUMP AND POWER SUPPLY CONNECTION



MCE/P 11 – MCE/P 15 – MCE/P 22

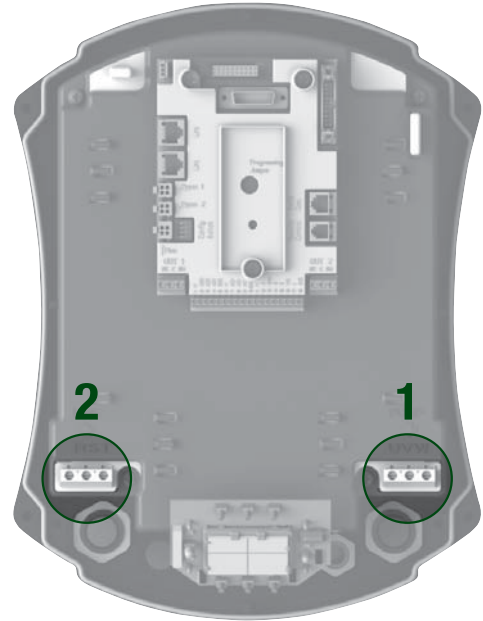
A Installation



- 1 Connect the power supply to the MCE/P
- 2 Connect electrically the MCE/P

MCE/P 30 – MCE/P 55

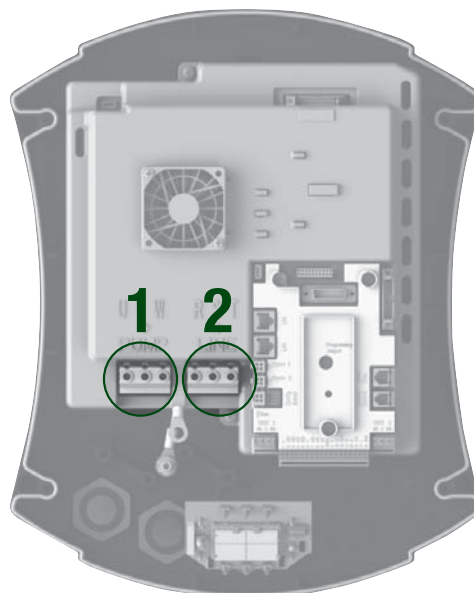
A Installation



- 1 Connect the power supply to the MCE/P
- 2 Connect electrically the MCE/P

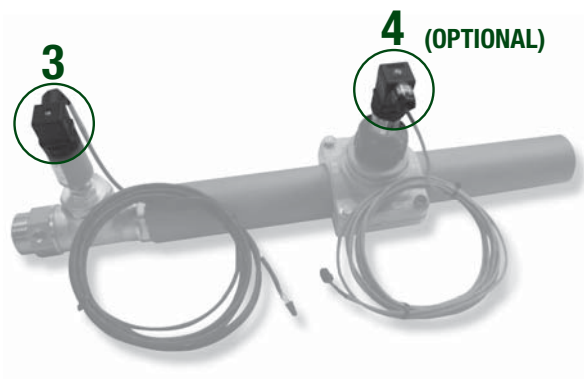
MCE/P 110 – MCE/P 150

A Installation



- 1 Connect the power supply to the MCE/P
- 2 Connect electrically the MCE/P

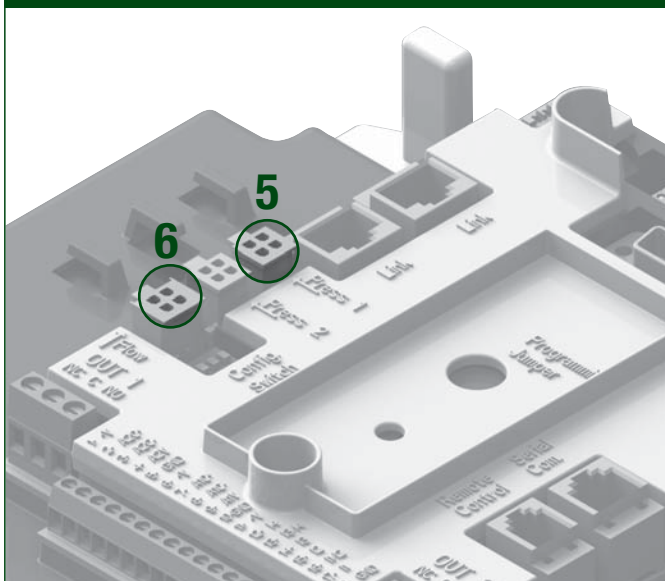
B | Sensors installation (OPTIONAL)



Installation of sensors on the pump delivery manifold

- 3** Pressure sensor (mandatory)
- 4** FLOW SENSOR (optional)

C Connection of the sensor to the MCE/P



- 5** PRESSURE SENSOR With 4 poles connector to press 1.
The pressure sensor is mandatory.
- 6** FLOW SENSOR with 6 poles connector (only if installed).
The flow sensor is optional.

7. How to program the MCE/P

Then the end user should close the front cover.

8. Switch on the power supply

Next step is to fix the amperometric protection. Press for 5 seconds:



On the screen appears the value **RC**

Adjust the amperage with ▾ and ▲.

9. Direction of Rotation of the motor

Press two times



On the screen appears the parameter **RT** And with the ▾ and ▲ select the direction of rotation.

To choose the correct direction of rotation, the end user could do in the following way: after opening one tap, the end user could check on the display the value of the frequency (FR). The right direction of rotation is the one that gives to lower FR value.

10. Flow sensor

IF THE FLOW SENSOR IS INSTALLED - Press many times



until it is not achieved the parameter **FD**. (Pipe dimension).

Choose the value of the pipe diameter where the sensor is assembled.

IF THE FLOW SENSOR IS NOT INSTALLED - Press



until it is not achieved the parameter **FL**. Fix this parameter, so that the flow sensor is absent.

11. Set point

Press **SET** to exit from Installer's menu.

Press **MODE** **SET** for 2 seconds and adjust the pressure.

SP is displayed; use keys ▾ and ▲ to set the pressure

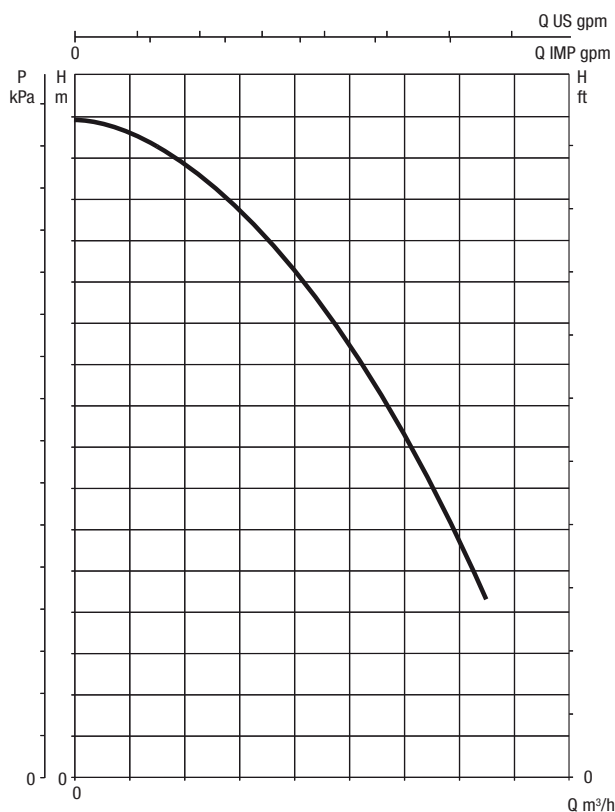


Fig. 6 Performance curves without inverter

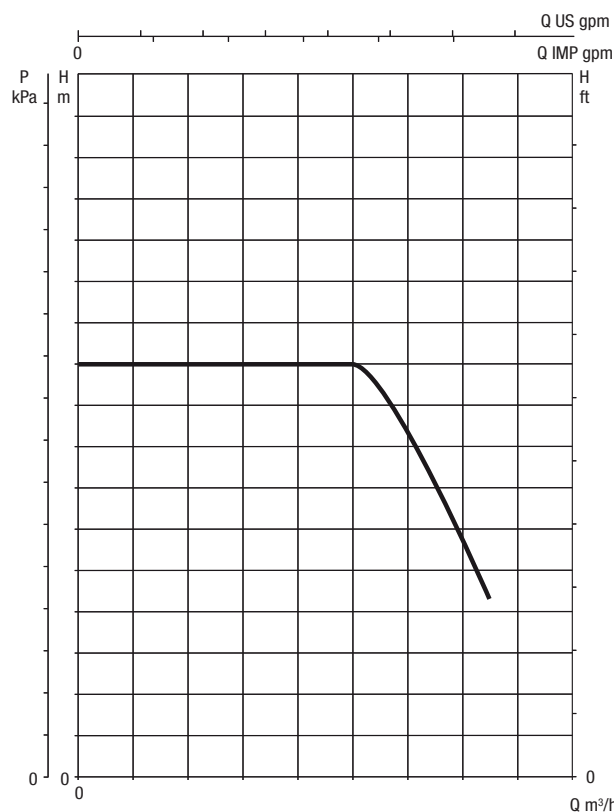


Fig. 7 Performance curves with inverter

PERFORMANCE CURVE

When an inverter is installed the performance curve changes as shown in figure 7.

The inverter can maintain constant pressure as flow rate changes.

Working pressure can be regulated by the user.

A good pressure set-point is between 1/3 and 2/3 of the maximum pump pressure head. This serves to maintain a high level of pump efficiency while maximising power savings.

Note: The MCE/P inverter does not stop the pump if the pressure value is not reached although a flow is detected.

This strategy prevents service outages in the case of high flow applications.

PROTECTION SYSTEMS

MCE/P is equipped with protection systems designed to preserve the pump, motor, power line and MCE/P itself. When one or more protections trip, the one with the highest priority is shown on display. Depending on the type of error, the electric pump may shut down, but when normal conditions are restored, the error state may clear automatically, immediately or after a set time interval following automatic reset.

In the case of a block due to water supply failure (BL), block due to pump motor current overload (OC), block due to final output stage current overload (OF), block due to direct short circuit between the phases on the output terminal (SC), the user can attempt to manually reset the error condition by pressing and releasing buttons + and - simultaneously. If the error condition persists, the cause of the fault must be located and eliminated.

WARNING ON THE FAULT HISTORY QUEUE

| DISPLAY | DESCRIPTION |
|---------|------------------------------|
| PD | IRREGULAR SHUTDOWN |
| FA | PROBLEMS WITH COOLING SYSTEM |

ERROR CONDITIONS

| DISPLAY | DESCRIPTION |
|---------|---|
| bL | BLOCKAGE DUE TO LACK OF WATER |
| bP | BLOCK DUE TO PRESSURE SENSOR READING ERROR |
| LP | BLOCKAGE DUE TO LOW SUPPLY VOLTAGE |
| HP | BLOCK DUE TO HIGH INTERNAL POWER SUPPLY VOLTAGE |
| ot | BLOCKAGE DUE TO OVERHEATING OF THE POWER OUTPUT STAGES |
| ob | BLOCKAGE DUE TO OVERHEATING OF THE PRINTED CIRCUIT |
| oC | BLOCKAGE DUE TO OVERCURRENT IN THE ELECTRO PUMP MOTOR |
| oF | BLOCKAGE DUE TO OVERCURRENT IN THE OUTPUT STAGES |
| SC | BLOCKAGE DUE TO DIRECT SHORT CIRCUIT BETWEEN THE PHASES OF OUTPUT TERMINALS |
| EC | BLOCKAGE DUE TO INCORRECT SETTING OF THE RATED CURRENT (RC) |
| Ei | BLOCK DUE TO "I" INTERNAL ERROR |
| Vi | BLOCK DUE TO "I" INTERNAL VOLTAGE OUTSIDE TOLERANCE |

AUTOMATIC RESET OF ERROR CONDITIONS

| DISPLAY | DESCRIPTION | SEQUENCE OF AUTOMATIC RESET |
|---------|---|---|
| bL | Blockage due to lack of water | One attempt every 10 min. for a total of 6 attempts - One attempt every 1 hour for a total of 24 attempts - One attempt every 24 hours for a total of 30 attempts |
| bP | Shutdown due to fault of the pressure sensor | - Reset 10 seconds after correct conditions return |
| LP | Shutdown due to low supply voltage $V_n - 20\%$ | - Reset when line voltage over $V_n - 15\%$ is restored |
| HP | Shutdown due to high voltage, $V_n + 15\%$ | - Reset when line voltage less than $V_n + 15\%$ is restored |
| Ot | Shutdown due to overheating of the power stages ($t_E > 100$) | - Reset when the temperature of the power stages falls below 85°C again |
| ob | Shutdown due to overheating of the printed circuit ($BT > 120^\circ\text{C}$) | - Reset when the temperature of the printed circuit falls below 100°C again |
| OC | Shutdown due to current overload | - An attempt every 10 minutes for a total of 6 attempts |
| oF | Shutdown due to current overload in the output stages | - An attempt every 10 minutes for a total of 6 attempts |

PROTECTION SYSTEMS

“bL” Block due to water failure

In zero flow conditions, with pressure lower than the set regulation value, a water failure signal is emitted and the system shuts down the pump. The delay interval without pressure and flow can be set in the parameter TB of the TECHNICAL ASSISTANCE menu.

If the user inadvertently enters a pressure setpoint higher than the pressure that the electric pump can supply on closure, the system indicates “block due to water failure” (BL) even if this is not precisely the problem. In this case, lower the regulation pressure to a reasonable value, which does not normally exceed 2/3 of the head of the electrical pump installed.

“bP” Block due to fault on pressure sensor

If MCE/P detects a fault on the pressure sensor, the pump remains blocked and the error signal “BP” is displayed. This status starts as soon as the problem is detected and is reset automatically when the correct conditions are restored.

“LP” Block due to low power supply voltage

This occurs when the voltage on the line to the power supply terminal falls below 164 Vac. Reset is only automatic when the voltage to the terminal exceeds 184 Vac.

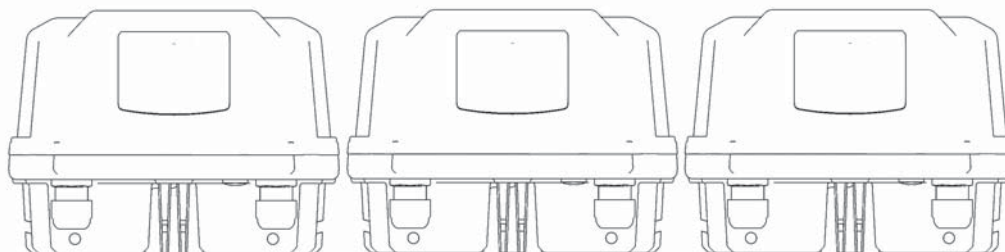
“HP” Block due to high internal power supply voltage

This occurs when the internal power supply voltage has values outside the specified range. Reset is only automatic when the voltage returns to within admissible values. This may be caused by changes in power supply voltage or excessively sudden pump shutdown.

“SC” Block due to direct short circuit between the phases on the output terminal

MCE/P is equipped with a protection against direct short circuits, which may occur between the phases U, V, and W of the output terminal “PUMP”. When this block signal is sent, the user can attempt reset by pressing buttons + and – simultaneously which in any event does not have any effect until 10 seconds has passed since the moment of the short circuit.

3 Groups for inverters



Introduction to multi inverter systems

A multi inverter system comprises a pump set made up of a series of pumps with delivery outlets all conveying to a single manifold. Each pump of the set is connected to its own inverter and the various inverters communicate via a special connection (Link).

The maximum number of pump-inverter elements possible in a group is 8.

A multi inverter system is mainly used to:

- Increase the hydraulic performance with respect to a single inverter
- Ensure operation continuity in the event of a fault on a pump or inverter
- Partition maximum power

Setting up a multi inverter system

The pumps must all be connected to a single delivery manifold and the flow sensor must be placed on the outlet of the latter to read the flow to the entire pump set. In the case of using multiple flow sensors, these must be installed on the delivery of each pump.

The pressure sensor must be connected to the outlet manifold. If more than one pressure sensor is used, these must also be installed on the manifold or in any event on a pipeline that is connected to it.

Note: If multiple pressure sensors are read, take care that the pipeline on which they are mounted is not equipped with non-return valves between one sensor and the next; otherwise different pressure values may be read which lead to false average readings and incorrect settings.

For optimal operation of the pressure set, the following must be the same for each inverter-pump pair:

- type of pump and motor
- hydraulic connections
- rated frequency
- minimum frequency
- maximum frequency

Although this is the optimal condition, some of the above parameters may differ.

Sensors

The sensors to be connected are the same versions used in stand-alone versions, i.e. pressure sensor and flow sensor.

Flow sensors(OPTIONAL)

The flow sensors are optionals and can be connected in two ways:

- one sensor only
- the same number of sensors as inverters

The setting is entered on parameter FI. No other types of system are admitted.

The single flow sensor must be installed on the delivery manifold and it must intercept the hydraulic flow of the entire booster set. The electrical connection can be made independently on any of the inverters.

Multiple sensors are useful when a specific flow rate is required on each pump, and enhance protection against dry running operation. To use multiple flow sensors, parameter FI must be set to multiple sensors and each flow sensor must be connected to the inverter that controls the pump delivery where the sensor is located.

Pressure sensors

The pressure sensor must be inserted on the delivery manifold. There can be more than one pressure sensor, and in this case the pressure reading will be the average value of all those present. To use multiple pressure sensors, the connectors are simply inserted in the relative inputs and no parameter needs to be set. The number of pressure sensors installed can vary as required between one and the maximum number of inverters present.

Multi-inverter settings

When a multi inverter system is switched on, the addresses are assigned automatically and, by means of an algorithm, an inverter is nominated as the settings leader. The leader decides on the frequency and order of start-up of each inverter in the series.

The settings mode is sequential (inverters start one at a time). When start-up conditions are enabled, the first inverter starts, and when this reaches maximum frequency, the next one starts, and so on. The order of start-up is not necessarily ascending according to the machine address, but depends on the hours of operation.

When the minimum frequency FL is used, and there is only one inverter operative pressure surges may occur. Depending on the case, pressure surges may be inevitable and may occur at the minimum frequency when this value, in relation to the hydraulic load, causes a pressure level greater than the required value. On multi inverter systems, this problem remains limited to the first pump that is started up, as on the subsequent pumps the situation is as follows: when the previous pump reaches the maximum frequency, the next one starts up at the minimum frequency to then reach the maximum frequency. When the frequency of the pump at maximum is reduced (obviously through to the minimum frequency limit) the pump activation overlaps, which while observing minimum frequency rates, does not cause pressure surges.

Assigning the start-up order

Each time the system is activated, each inverter is associated a starting order. This setting establishes the order of inverter start-up.

The starting order is modified during use according to requirements, by the two following algorithms:

- Reaching of maximum operating time
- Reaching of maximum inactivity time

Maximum operating time

According to parameter ET (maximum operating time), each inverter has an hour counter, and the starting order is updated on the basis of these values according to the following algorithm:

- if at least half of the value ET is exceeded, priority is changed on the first shutdown of the inverter (switch to standby).
- if the value ET is reached without stopping, the inverter stops unconditionally and this sets to the minimum restart priority (switch during operation).

Reaching of maximum inactivity time

The multi inverter system has an anti-stagnant algorithm that is aimed at maintaining pump efficiency and integrity of the pumped liquid. It acts by enabling rotation of the pump starting order to ensure a delivery to all pumps of at least one minute of flow every 23 hours. This is implemented regardless of the inverter configuration (enabled or reserve). Priority switch envisages that the inverter stationary for 23 hours is set to maximum priority in the starting order. This means that it is the first to be started up as soon as flow delivery is required. The inverters configured as reserve have priority over the others. The algorithm terminates action when the inverter has delivered at least one minute of flow.

After the anti-stagnant interval, if the inverter is configured as reserve, it is set to minimum priority to avoid premature wear.

Reserves and number of inverters involved in pumping

The multi inverter system reads how many elements are connected in communicating mode and calls this number N .

Then, on the basis of parameters NA and NC it decides how many and which inverters must work at a given time.

NA represents the number of inverters involved in pumping NC represents the maximum number of inverters that can run simultaneously.

In a series, if there are NA active inverters and NC simultaneous inverters, when NC is less than NA , this means that a maximum of NC inverters will start up simultaneously, and these will switch between NA elements. If an inverter is configured with reserve priority, it will set as last in the starting order, therefore for example, if there are 3 inverters and one of these is configured as reserve, the reserve unit will start in third place; otherwise if set to $NA=2$ the reserve will not start up unless one of the two active units sets to fault status.

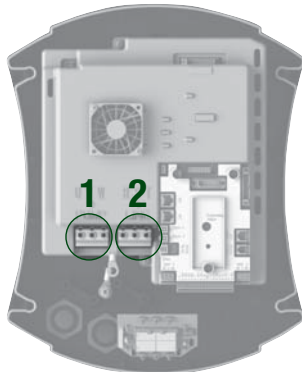
FZ: Zero flow frequency setting

It expresses the frequency below which it may be considered that there is zero flow in the system.

It can be set only if FI has been set to operate without a flow sensor. If FI has been set to operate with a flow sensor, the parameter FZ is blocked. The parameter disabled message is indicated by an icon showing a padlock.

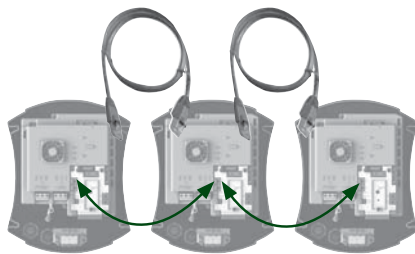
If $FZ = 0$ Hz is set the inverter will use the self-adaptive operating mode, instead if $FZ \neq 0$ Hz is set then the inverter will use the minimum frequency operating mode

A Installation



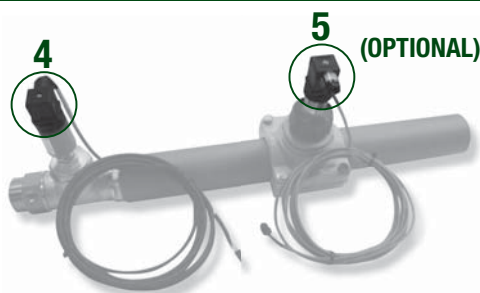
- 1 Connect the power supply to the MCE/P
- 2 Connect electrically the MCE/P

B Link connection



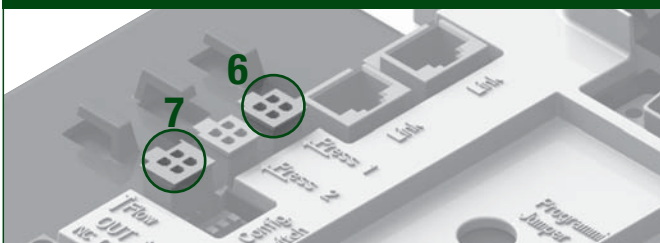
- 3 Connect with the cable each MCE/P
It is possible to insert in every input link.

C Sensors installation (OPTIONAL)



- Installation of sensors on the pump delivery manifold
- 4 Pressure sensor (mandatory)
 - 5 FLOW SENSOR (optional)

C Connection of the sensor to the MCE/P



- 6 PRESSURE SENSOR With 4 poles connector to press 1.
- 7 FLOW SENSOR with 6 poles connector (OPTIONAL).

8. How to program the MCE/P

Then the end user should close the front cover and switch on the power supply **To only one inverter at time.**

9. Fix the amperometric protection

Press for 5 seconds:



On the screen appears the value **RC**
Adjust the amperage with ∇ and Δ .
You can read the rated current in the label of the pump.

10. Direction of Rotation of the motor

Press

On the screen appears the parameter **RT** and with the ∇ and Δ select the direction of rotation. To choose the correct direction of rotation, the end user could do in the following way: after opening one tap, the end user could check on the display the value of the frequency (FR). The right direction of rotation is the one that gives to lower FR value.

11. Flow sensor (OPTIONAL)

- IF THE FLOW SENSOR IS INSTALLED - Press many times



finche non viene visualizzato il parametro dimensione del tubo in Pollici **FD**
selezionare il diametro della tubatura dove è installato il sensore di flusso.

- **SENSORE DI FLUSSO ASSENTE** Premere tante volte il tasto



until it is not achieved the parameter **FL**. (Pipe dimension). Choose the value of the pipe diameter where the sensor is assembled.

12. press the key repeatedly until the FZ parameter is displayed; set the frequency of FZ shutdown, when the pumps should stop.

13. Set point.

Press to exit from Installer's menu on the first inverter.

Press for 2 seconds and adjust the pressure .

SP is displayed; use keys ∇ and Δ to set the pressure. Repeat the settings of RC, RT, FD, SP for each inverter, powering up only the inverter subject to settings.

14. Switch on the power supply on each MCE/P

The system is ready to work normally. If necessary, change the other parameters as described on manual instruction.

MCE/P systems are equipped with 4 inputs and 2 outputs to enable a number of solutions for interface with more complex installations.

Figure 11: Example of output connections and Figure 12: Example of input connections show examples of two possible configurations of the inputs and outputs.

For the installer it is sufficient to wire the required input and output contacts and then configure the functions as necessary.

Note: The +19 [Vdc] power supplies to pins 11 and 18 and J5 (18-pole terminal board) can deliver a maximum of 50 [mA].

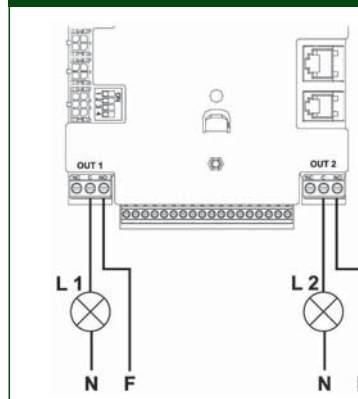
Photocoupled input contact specifications

The connections of the inputs listed below refer to the 18-pole terminal board J5, with numbering starting from pin 1 from the left. The base of the terminal board also bears the text of the corresponding inputs.

- I 1: Pins 16 and 17
- I 2: Pins 15 and 16
- I 3: Pins 13 and 14
- I 4: Pins 12 and 13

The inputs can be activated in DC or AC.

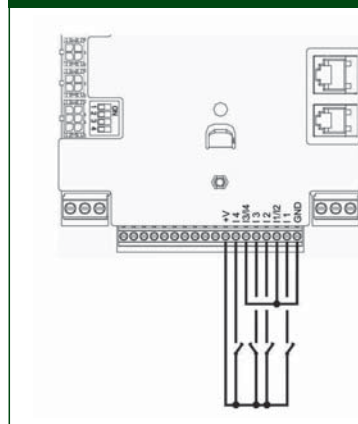
11 Example of output connections



With reference to the example in Figure : Example of output connections and using the default settings (O1 = 2: contact NO; O2 = 2; contact NO) the following is obtained:

L1 lights up when the pump is blocked (e.g. "BL":water failure block).
L2 si accende quando la pompa è in marcia ("GO").

12 Example of input connections



With reference to the example in Figure: Example of input connections and using the default input settings (I1 = 1; I2 = 3; I3 = 5; I4=10) the following is obtained: When the switch on I1 is turned off the pump blocks and the signal "F1 is displayed"

When the switch is closed on I2 the control pressure becomes "P2"
When the switch is closed on I3 the pump trips and error code "F3" is displayed
When the switch is closed on I4 after time T1 the pump trips and error code F4 is displayed.

Parametri

| MENUS AND DEFAULT VALUES | | | | |
|--|------------------------------------|--------------------|----------|----------|
| DESCRIPTION | | Factory parameters | | |
| Indications on the display in normal operation | | MCE/P 11 | MCE/P 15 | MCE/P 22 |
| LA | Language | ITA | ITA | ITA |
| SP | Setpoint pressure [bar] | 3,0 | 3,0 | 3,0 |
| P1 | Setpoint P1 [bar] | 2,0 | 2,0 | 2,0 |
| P2 | Setpoint P2 [bar] | 2,5 | 2,5 | 2,5 |
| P3 | Setpoint P3 [bar] | 3,5 | 3,5 | 3,5 |
| P4 | Setpoint P4 [bar] | 4,0 | 4,0 | 4,0 |
| FP | Test frequency in manual mode | 40,0 | 40,0 | 40,0 |
| RC | Rated current of electric pump [A] | 0,0 | 0,0 | 0,0 |
| RT | Direction of rotation | 0 (UVW) | 0 (UVW) | 0 (UVW) |
| FN | Rated frequency [Hz] | 50,0 | 50,0 | 50,0 |
| OD | Type of system | 1 (Rigid) | | |
| RP | Restart pressure [bar] | 0,5 | 0,5 | 0,5 |
| AD | Address | 0 (Auto) | | |
| PR | Pressure sensor | 1 (501 R 25 bar) | | |
| MS | Measurement system | 0 (International) | | |
| FI | Flow sensor | 1 (Flow X3 F3.00) | | |
| FD | Pipeline diameter [inch] | 2 | 2 | 2 |
| FK | K-factor [pulse/l] | 24,40 | 24,40 | 24,40 |

Parameters

| MENUS AND DEFAULT VALUES | | | | |
|---|---|--------------------|-----------|-----------|
| DESCRIPTION | | Factory parameters | | |
| Indicazioni display nel normale funzionamento | | MCE/P 11 | MCE/P 15 | MCE/P 22 |
| FZ | Minimum shutdown flow [l/min] | 0 | 0 | 0 |
| FT | Delay for water failure block [s] | 5 | 5 | 5 |
| S0 | Dry running factor | 22 | 22 | 22 |
| MP | Minimum pressure pump stop [bar] | 0,0 | 0,0 | 0,0 |
| TB | Shutdown delay [s] | 10 | 10 | 10 |
| T1 | Shutdown time after low pressure signal | 2 | 2 | 2 |
| T2 | Shutdown delay [s] | 10 | 10 | 10 |
| GP | Proportional gain coefficient | 0,6 | 0,6 | 0,6 |
| GI | Integral gain coefficient | 1,2 | 1,2 | 1,2 |
| FS | Maximum rotation frequency [Hz] | 50,0 | 50,0 | 50,0 |
| FL | Minimum rotation frequency [Hz] | 0,0 | 0,0 | 0,0 |
| NA | Active inverters | N | N | N |
| NC | Simultaneous inverters | NA | NA | NA |
| IC | Reserve configuration | 1 (Auto) | 1 (Auto) | 1 (Auto) |
| ET | Exchange time [h] | 2 | 2 | 2 |
| CF | Carrier [kHz] | 20 | | |
| AC | Acceleration | 3 | | |
| AE | Anti-blocking function | 1 (Abilitato) | 3 (P Aux) | 3 (P Aux) |
| I1 | Function I1 | 1 (Float) | | |
| I2 | Function I2 | 3 (P Aux) | | |
| I3 | Function I3 | 5 (Disable) | | |
| I4 | Function I4 | 10 (Low press) | | |
| O1 | Output 1 function | 2 | 2 | 2 |
| O2 | Output 2 function | 2 | 2 | 2 |

MCE/P 30 – MCE/P 55

| MENUS AND DEFAULT VALUES | | | |
|--|---|--------------------|------------|
| DESCRIPTION | | Factory parameters | |
| Indications on the display in normal operation | | MCE/P 30 | MCE/P 55 |
| LA | Language | ITA | ITA |
| SP | Setpoint pressure [bar] | 3,0 | 3,0 |
| P1 | Setpoint P1 [bar] | 2,0 | 2,0 |
| P2 | Setpoint P2 [bar] | 2,5 | 2,5 |
| P3 | Setpoint P3 [bar] | 3,5 | 3,5 |
| P4 | Setpoint P4 [bar] | 4,0 | 4,0 |
| FP | Test frequency in manual mode | 40,0 | 40,0 |
| RC | Rated current of electric pump [A] | 0,0 | 0,0 |
| RT | Direction of rotation | 0 (U/VW) | 0 (U/VW) |
| FN | Rated frequency [Hz] | 50,0 | 50,0 |
| OD | Type of system | 1 (Rigid) | |
| RP | Restart pressure [bar] | 0,5 | 0,5 |
| AD | Address | 0 (Auto) | |
| PR | Pressure sensor | 1 (501 R 25 bar) | |
| MS | Measurement system | 0 (International) | |
| FI | Flow sensor | 1 (Flow X3 F3.00) | |
| FD | Pipeline diameter [inch] | 2 | 2 |
| FK | K-factor [pulse/l] | 24,40 | 24,40 |
| FZ | Minimum shutdown flow [l/min] | 0 | 0 |
| FT | Delay for water failure block [s] | 5 | 5 |
| SO | Dry running factor | 22 | 22 |
| MP | Minimum pressure pump stop [bar] | 0,0 | 0,0 |
| TB | Shutdown delay [s] | 10 | 10 |
| T1 | Shutdown time after low pressure signal | 2 | 2 |
| T2 | Shutdown delay [s] | 10 | 10 |
| GP | Proportional gain coefficient | 0,6 | 0,6 |
| GI | Integral gain coefficient | 1,2 | 1,2 |
| FS | Maximum rotation frequency [Hz] | 50,0 | 50,0 |
| FL | Minimum rotation frequency [Hz] | 0,0 | 0,0 |
| NA | Active inverters | N | N |
| NC | Simultaneous inverters | NA | NA |
| IC | Reserve configuration | 1 (Auto) | 1 (Auto) |
| ET | Exchange time [h] | 2 | 2 |
| CF | Carrier [kHz] | 10 | |
| AC | Acceleration | 3 | |
| AE | Anti-blocking function | 1 (Active) | 1 (Active) |
| I1 | Function I1 | 1 (Float) | |
| I2 | Function I2 | 3 (P Aux) | |
| I3 | Function I3 | 5 (Disable) | |
| I4 | Function I4 | 10 (Bassa press) | |
| O1 | Output 1 function | 2 | 2 |
| O2 | Output 2 function | 2 | 2 |

MCE/P 110 – MCE/P 150

| MENUS AND DEFAULT VALUES | | | |
|--|---|--------------------|------------|
| DESCRIPTION | | Factory parameters | |
| Indications on the display in normal operation | | MCE/P 110 | MCE/P 150 |
| LA | Language | ITA | ITA |
| SP | Setpoint pressure [bar] | 3,0 | 3,0 |
| P1 | Setpoint P1 [bar] | 2,0 | 2,0 |
| P2 | Setpoint P2 [bar] | 2,5 | 2,5 |
| P3 | Setpoint P3 [bar] | 3,5 | 3,5 |
| P4 | Setpoint P4 [bar] | 4,0 | 4,0 |
| FP | Test frequency in manual mode | 40,0 | 40,0 |
| RC | Rated current of electric pump [A] | 0,0 | 0,0 |
| RT | Direction of rotation | 0 (U/VW) | 0 (U/VW) |
| FN | Rated frequency [Hz] | 50,0 | 50,0 |
| OD | Type of system | 1 (Rigid) | |
| RP | Restart pressure [bar] | 0,5 | 0,5 |
| AD | Address | 0 (Auto) | |
| PR | Pressure sensor | 1 (501 R 25 bar) | |
| MS | Measurement system | 0 (International) | |
| FI | Flow sensor | 1 (Flow X3 F3.00) | |
| FD | Pipeline diameter [inch] | 2 | 2 |
| FK | K-factor [pulse/l] | 24,40 | 24,40 |
| FZ | Minimum shutdown flow [l/min] | 0 | 0 |
| FT | Delay for water failure block [s] | 5 | 5 |
| SO | Dry running factor | 22 | 10 |
| MP | Minimum pressure pump stop [bar] | 0,0 | 2 |
| TB | Shutdown delay [s] | 10 | 10 |
| T1 | Shutdown time after low pressure signal | 2 | 0,6 |
| T2 | Shutdown delay [s] | 10 | 1,2 |
| GP | Proportional gain coefficient | 0,6 | 50,0 |
| GI | Integral gain coefficient | 1,2 | 0,0 |
| FS | Maximum rotation frequency [Hz] | 50,0 | N |
| FL | Minimum rotation frequency [Hz] | 0,0 | NA |
| NA | Active inverters | N | 1 (Auto) |
| NC | Simultaneous inverters | NA | 2 |
| IC | Reserve configuration | 1 (Auto) | 5 |
| ET | Exchange time [h] | 2 | 3 |
| CF | Carrier [kHz] | 5 | |
| AC | Acceleration | 3 | |
| AE | Anti-blocking function | 1 (Active) | 1 (Active) |
| I1 | Function I1 | 1 (Float) | |
| I2 | Function I2 | 3 (P Aux) | |
| I3 | Function I3 | 5 (Disable) | 2 |
| I4 | Function I4 | 10 (Low press) | 2 |
| O1 | Output 1 function | 2 | 2 |
| O2 | Output 2 function | 2 | 2 |





WATER • TECHNOLOGY

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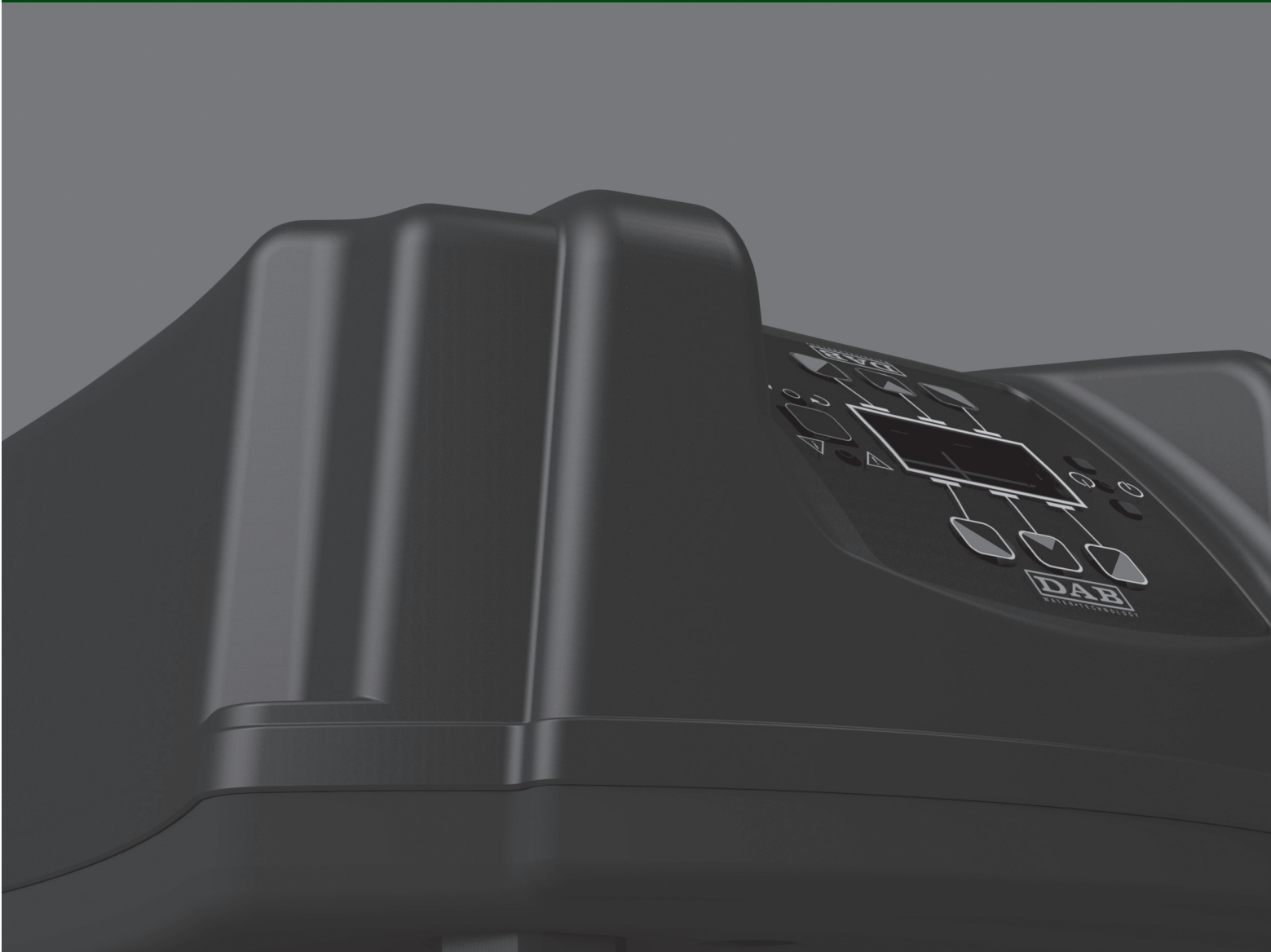
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INVERTER MCE/C

MCE/C 11-MCE/C 15-MCE/C 22

MCE/C 30-MCE/C 55

MCE/C 110-MCE/C 150





Description

The new MCE/C inverters are the latest technological challenge in the DAB inverters universe. They constitute the new generation of inverters for use with circulator pumps and stand out for ease of use, power, and simplicity of installation and management.

MCE /C inverters are designed for use with circulator pumps to enable simple control of differential pressure, thereby adapting pump performance to match effective system requirements.

The solution of mounting on the motor base greatly simplifies installation of the pump with MCE/C in minimal times. The inverters feature IP55 protection rating. Ease of programming is guaranteed by the use of an interface similar to DAB Dialogue and a graphic display.

MCE/C inverters feature dual microprocessor architecture to guarantee maximum efficiency and reliability. Sturdy and reliable construction is combined with modern and innovative styling to complete the product also in terms of aesthetics. MCE/C inverters protect the pump thanks to integrated safety devices. They are also able to prolong the useful lifetime of the pump thanks to the elimination of water hammer and rotation of the pump at the minimum rpm necessary to meet the requirements of the user. Last but not least, these inverters save power by keeping pump consumption to the minimum levels strictly necessary to meet user requirements.

Equipped with communication module for the creation of twin pumpsets

Benefits

Why the Dab inverter?

The MCE/P units are air cooled. These extremely robust panel-mounting inverters feature a metal body and are suitable for heavy-duty applications. To enable operation these need a differential pressure sensor MCE/C. MCE/P combines practicality with easy installation and management. MCE/P ensure the utmost practicality and increase the average working life of the system, permitting also significant savings in power consumption.

Advantages

- Easily installed in existing systems
- Constant pressure
- Power consumption reduced by up to 60%
- Built-in protections
- Operates with all pumps
- Robust
- Facility to create sets with interchange of up to 8 pumps
- IP55 protection rating



Characteristics

MCE/C 11 – MCE/C 15 – MCE/C 22

- Self-ventilated panel-mounting inverters for hydraulic pumps.
- Per pompe trifase fino a 3HP - 2,2kW
- OLED graphic display
- Input power supply 1 x 230V 50-60Hz
- Pump voltage 3 x 230V
- Electric pump nominal frequency 50-200 Hz
- Control range in accordance with the sensor utilised, with standard range of 1-24bar
- Protections against voltage surges
- Adjustable overload protection
- Extended connectivity
- Protection rating: IP55
- Short circuit between output phases
- Overtemperature protection
- Possibility of creating intercommunicating twin pumpsets

MCE/C 30 – MCE/C 55

- Self-ventilated panel-mounting inverters for hydraulic pumps.
- For three-phase pumps up to 7.5 HP - 5.5 kW
- OLED graphic display
- Input power supply 3 x 400V 50-60Hz
- Pump voltage 3 x 400V
- Electric pump nominal frequency 50-200 Hz
- Control range in accordance with the sensor utilised, with standard range of 1-24bar
- Protections against voltage surges
- Adjustable overload protection
- Extended connectivity
- Protection rating: IP55
- Short circuit between output phases
- Overtemperature protection
- Possibility of creating intercommunicating twin pumpsets

MCE/C 110 – MCE/C 150

- Self-ventilated panel-mounting inverters for hydraulic pumps.
- For three-phase pumps up to 20HP – 15kW
- OLED graphic display
- Input power supply 3 x 400V 50-60Hz
- Pump voltage 3 x 400V
- Electric pump nominal frequency 50-200 Hz
- Control range in accordance with the sensor utilised, with standard range of 1-24bar
- Protections against voltage surges
- Adjustable overload protection
- Extended connectivity
- Protection rating: IP55
- Short circuit between output phases
- Overtemperature protection
- Possibility of creating intercommunicating twin pumpsets

| Model | Max. motor current A | Max. motor power kW | Power supply V | Pump Input V | Parallel user interface | Maximum dimensions L x H x P |
|-----------------|-------------------------|------------------------|----------------------------|-----------------------------|-------------------------|---------------------------------|
| MCE/C 11 | 6.5 | 1.1 | <i>Mono-phase</i> 1x230 | <i>Three-phase</i> 3x230 | SI | 205 x 205 x 265 |
| MCE/C 15 | 8,0 | 1.5 | <i>Mono-phase</i> 1x230 | <i>Three-phase</i> 3x230 | SI | 205 x 205 x 265 |
| MCE/C 22 | 10.5 | 2.2 | <i>Mono-phase</i> 1x230 | <i>Three-phase</i> 3x230 | SI | 205 x 205 x 265 |

| | | MCE/C 11 | MCE/C 15 | MCE/C 22 |
|--|--|------------------------------------|---------------|---------------|
| <i>Inverter power feeding</i> | <i>Voltage [VAC] (Tolerance +10/-20%)</i> | 220-240 | | |
| | <i>Phases</i> | 1 | | |
| | <i>Frequency [Hz]</i> | 50 - 60 Hz | | |
| | <i>Current [A]</i> | 12 | 18,7 | 22 |
| <i>Inverter power output</i> | <i>Voltage [VAC] (Tolerance +10/-20%)</i> | 0 - V power supply | | |
| | <i>Phases</i> | 3 | | |
| | <i>Frequency [Hz]</i> | 0-200 | | |
| | <i>Current [A]</i> | 6,5 | 8 | 10.5 |
| | <i>Max electrical power output [kVA] (400 Vrms)</i> | 1,5 | 2 | 2.8 |
| <i>Mechanical characteristics</i> | <i>Mechanical power rating P2</i> | 1,5 CV / 1,1 kW | 2 CV / 1,5 Kw | 3 CV / 2,2 kW |
| | <i>Unit weight [kg] (packing included)</i> | 5.0 | | |
| <i>Installation</i> | <i>Maximum dimensions [mm] (WxHxD)</i> | 205 x 205 x 265 | | |
| | <i>Operating position</i> | <i>Any position</i> | | |
| | <i>IP protection rating</i> | 55 | | |
| | <i>Maximum ambient temperature [°C]</i> | 40 | | |
| | <i>Maximum conductor section accepted by input and output terminals [mm²]</i> | 4 | | |
| | <i>Minimum cable diameter accepted by inlet and outlet cable glands [mm]</i> | 6 | | |
| <i>Control and operation hydraulic characteristics</i> | <i>Maximum cable diameter accepted by inlet and outlet cable glands [mm]</i> | 12 | | |
| | <i>Pressure control range [bar]</i> | 1 – 95% pressure sensor full scale | | |

| | | MCE/C 11 | MCE/C 15 | MCE/C 22 |
|----------------------------------|--|--|----------|----------|
| <i>Sensors</i> | <i>Types of pressure sensor</i> | <i>Ratiometric sensor</i> | | |
| | <i>Full scale of differential pressure sensors [bar]</i> | 4 / 10 | | |
| <i>Functions and protections</i> | <i>Connectivity</i> | <i>Serial interface - Remote control - Multi inverter connection</i> | | |
| | <i>Protections</i> | <i>Self-protected against current surges</i> <i>Internal electronics overtemperature</i> <i>Power supply voltage anomalies</i> <i>Direct shorting between output phases</i> | | |

TECHNICAL DATA

MCE/C 30 – MCE/C 55



| Model | Max. motor current A | Max. motor power kW | Power supply V | Pump Input V | Parallel user interface | Maximum dimensions L x H x P |
|-----------------|-------------------------|------------------------|----------------------|----------------------|-------------------------|---------------------------------|
| MCE/C 30 | 7,5 | 3 | Three-phase 3x400 | Three-phase 3x400 | SI | 270 x 355 x 195 |
| MCE/C 55 | 13,5 | 5,5 | Three-phase 3x400 | Three-phase 3x400 | SI | 270 x 355 x 195 |

| | | MCE/C 30 | MCE/C 55 |
|---|---|------------------------------------|-------------|
| Inverter power feeding | Voltage [VAC] (Tolerance +10/-20%) | 380-480 | |
| | Phases | 3 | |
| | Frequency [Hz] | 50 - 60 Hz | |
| | Current [A] | 11,5 - 9,0 | 17,0 - 13,0 |
| Inverter power output | Voltage [VAC] (Tolerance +10/-20%) | 0 - V power supply | |
| | Phases | 3 | |
| | Frequency [Hz] | 0-200 | |
| | Current [A] | 7,5 | 13,5 |
| | Max electrical power output [kVA] (400 Vrms) | 4,0 | 7,0 |
| Mechanical power rating P2 | 4 CV/3.0 Kw | 7,5 CV / 5,5 kW | |
| Mechanical characteristics | Unit weight [kg] (packing included) | 7,6 | |
| | Maximum dimensions [mm] (WxHxD) | 270 x 355 x 195 | |
| Installation | Operating position | Any position | |
| | IP protection rating | 55 | |
| | Maximum ambient temperature [°C] | 40 | |
| | Maximum conductor section accepted by input and output terminals [mm ²] | 6 | |
| | Minimum cable diameter accepted by inlet and outlet cable glands [mm] | 11 | |
| | Maximum cable diameter accepted by inlet and outlet cable glands [mm] | 17 | |
| Control and operation hydraulic characteristics | Pressure control range [bar] | 1 – 95% pressure sensor full scale | |

| | | MCE/C 30 | MCE/C 55 |
|---------------------------|---|--|----------|
| Sensors | Types of pressure sensor | Ratiometric sensor | |
| | Full scale of differential pressure sensors [bar] | 4 / 10 | |
| Functions and protections | Connectivity | Serial interface - Remote control - Multi inverter connection | |
| | Protections | Self-protected against current surges Internal electronics overtemperature Anomalous power supply voltage Direct shorting between output phases | |

| Model | Max. motor current A | Max. motor power kW | Power supply V | Pump Input V | Parallel user interface | Maximum dimensions L x H x P |
|------------------|-------------------------|------------------------|----------------------|----------------------|-------------------------|---------------------------------|
| MPE/C 110 | 24 | 11,0 | Three-phase 3x400 | Three-phase 3x400 | SI | 340 x 430 x 250 |
| MPE/C 150 | 32 | 15,0 | Three-phase 3x400 | Three-phase 3x400 | SI | 340 x 430 x 250 |

| | | MPE/C 110 | MPE/C 150 |
|---|---|------------------------------------|---------------|
| Inverter power feeding | Voltage [VAC] (Tolerance +10/-20%) | 380-480 | |
| | Phases | 3 | |
| | Frequency [Hz] | 50 - 60 Hz | |
| | Current [A] | 32,5-26,0 | 42,0-33,5 |
| Inverter power output | Voltage [VAC] (Tolerance +10/-20%) | 0 - V power supply | |
| | Phases | 3 | |
| | Frequency [Hz] | 0-200 | |
| | Current [A] | 24,0 | 32,0 |
| | Max electrical power output [kVA] (400 Vrms) | 14,0 | 19,0 |
| | Mechanical power rating P2 | 15 CV / 11 kW | 20 CV / 15 kW |
| Mechanical characteristics | Unit weight [kg] (packing included) | 12,0 | |
| | Maximum dimensions [mm] (WxHxD) | 340 x 430 x 250 | |
| Installation | Operating position | Any position | |
| | IP protection rating | 55 | |
| | Maximum ambient temperature [°C] | 40 | |
| | Maximum conductor section accepted by input and output terminals [mm ²] | 4 | |
| | Minimum cable diameter accepted by inlet and outlet cable glands [mm] | 16 | |
| | Maximum cable diameter accepted by inlet and outlet cable glands [mm] | 17 | |
| Control and operation hydraulic characteristics | Pressure control range [bar] | 1 – 95% pressure sensor full scale | |

| | | MPE/C 110 | MPE/C 150 |
|---------------------------|---|--|-----------|
| Sensors | Types of pressure sensor | Ratiometric sensor | |
| | Full scale of differential pressure sensors [bar] | 4 / 10 | |
| Functions and protections | Connectivity | Serial interface - Remote control - Multi inverter connection | |
| | Protections | Self-protected against current surges Internal electronics overtemperature Anomalous power supply voltage Direct shorting between output phases | |

Reducing motor speed, even marginally, can lead to an appreciable reduction in power consumption because the absorbed power of an electric motor is proportional to the rpm cubed. For example, a pump powered by the mains that runs at approximately 2950 rpm, will run approximately 20% slower (i.e. at 2360 rpm) when fed with a 40 Hz supply, leading to a saving of 40% in terms of absorbed power.

The motor speed reduction increases pump life significantly, thanks to the reduction of mechanical stress.

Pump performance in relation to variations in rpm

Pump rpm n has a very significant influence on pump performance. In the absence of cavitation phenomena the law of similarity is applicable, as shown in equation 1.

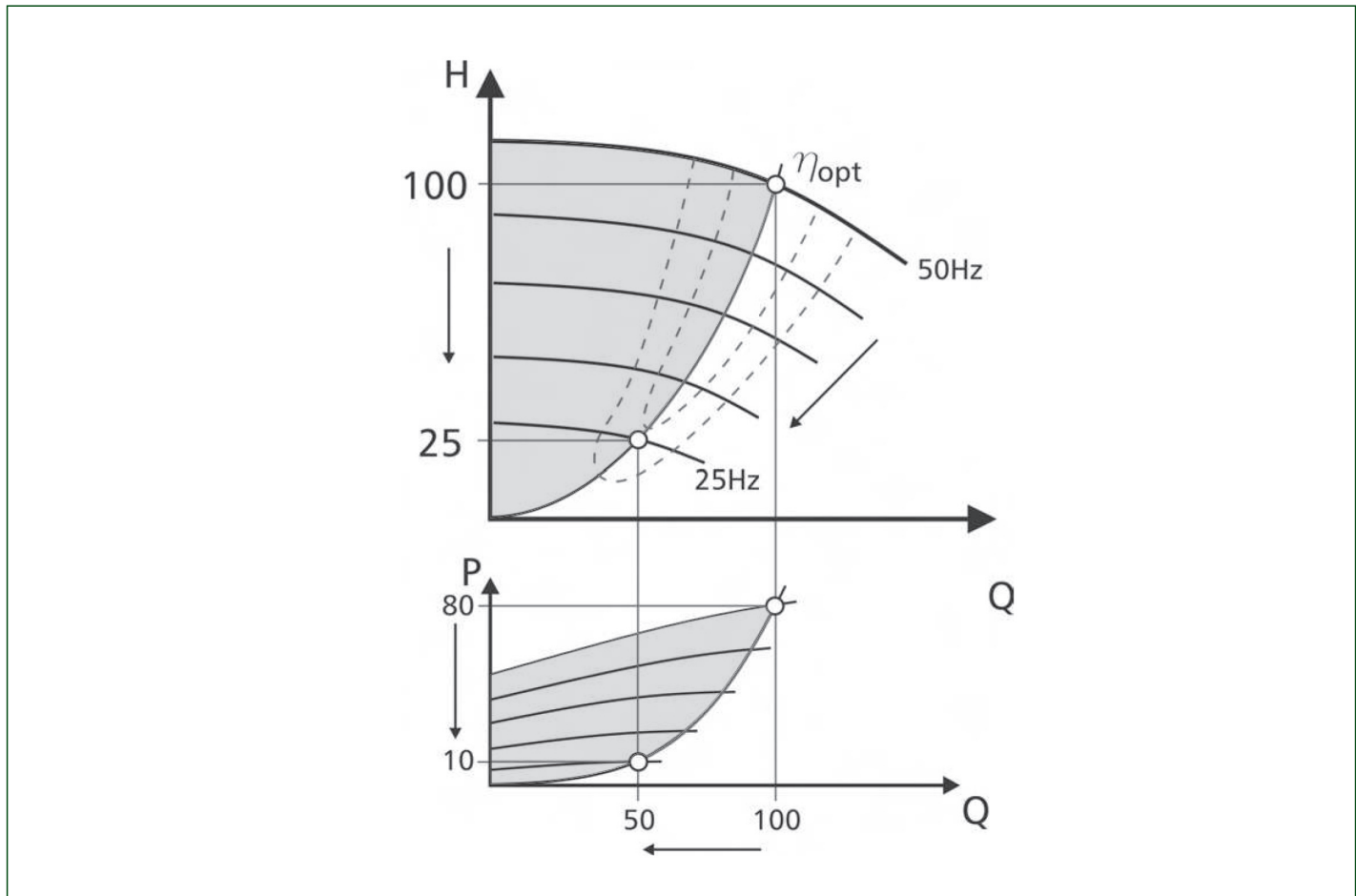
- Flow rate changes in a linear manner with changes in speed.
- Pressure changes in a squared relationship with changes in rpm.
- Power changes in a cubed relationship with changes in rpm.
- A small change in rpm produces a very large change in power.

Equation 1

$$\frac{Q_x}{Q} = \frac{n_x}{n} \quad Q = Q_x \frac{n_x}{n}$$

$$\frac{H_x}{H} = \left(\frac{n_x}{n}\right)^2 \quad H_x = H \left(\frac{n_x}{n}\right)^2$$

$$\frac{P_x}{P} = \left(\frac{n_x}{n}\right)^3 \quad P_x = P \left(\frac{n_x}{n}\right)^3$$



- a lowering of the flow acc. to the linear function
- a reduction of the head according to a quadratic function
- a reduction of the power consumption acc. to a cubic function!

The new MCE/C inverters are the latest milestone in DAB inverter design. They are the new generation of inverters for use with circulation pumps and offer outstanding user-friendliness, power and ease of installation and use. MCE/C inverters are designed to control circulation pumps and allow the pump's output to be adapted to the system's actual requirements through simple control of the differential pressure. They are mounted on the motor fan casing. This makes installation of pumps with MCE/C particularly quick and easy. The MCE/C device has IP55 protection. Trouble-free programming is ensured by the use of a simple, intuitive interface similar to that on Dialogue electronic circulators and a graphic display. MCE/C inverters are built with two microprocessors, guaranteeing unbeatable efficiency and reliability.

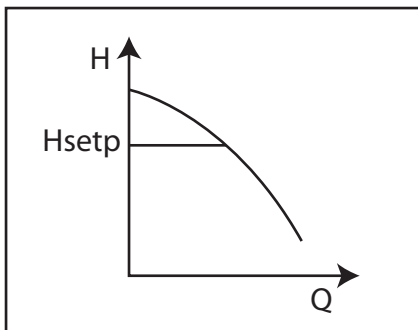
Reliable and rugged construction plus modern and innovative styling complete the product also from an aesthetic standpoint. MCE/C inverters protect the motor and the pump and extend their lifetime because they prevent hammer blows and operate the pump at the minimum rpm required to meet the user's demands. What's more, electric pumps controlled by the MCE/C inverter are environment-friendly, since by ensuring that the pump only consumes the power strictly necessary to meet the user's demands they cut electricity consumption significantly compared to fixed speed units. Possibility of creating twin units using the special MCE/C inverter connection cable.

OPERATING MODES

All the functions listed below can be consulted by all users (even the least skilled) by just scrolling through the MCE/C menu. Calibration and parameter modification are protected functions, permitted only to skilled users.

Constant differential pressure control mode $\Delta P-c$

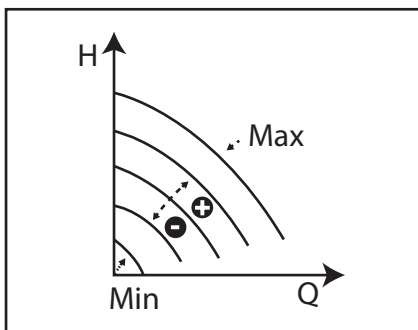
$\Delta P-c$ control mode keeps the system's differential pressure constant at the H value set (setp) as the flow rate varies. This is the standard control mode, for normal use. It can be set directly from the MCE/C's control panel. The inverter maintains the differential pressure (H setp) constant as the flow rate varies.



This control mode is particularly useful in the following types of installations:

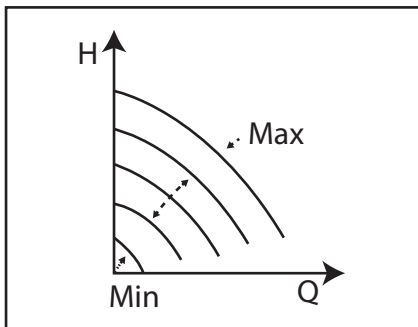
- A** Two-pipe central heating systems with thermostatic valves
- B** Under-floor central heating systems with thermostatic valves
- C** Single-pipe central heating systems with thermostatic and calibration valves
- D** Installations having primary circuit pumps

Constant curve control mode



Constant curve control

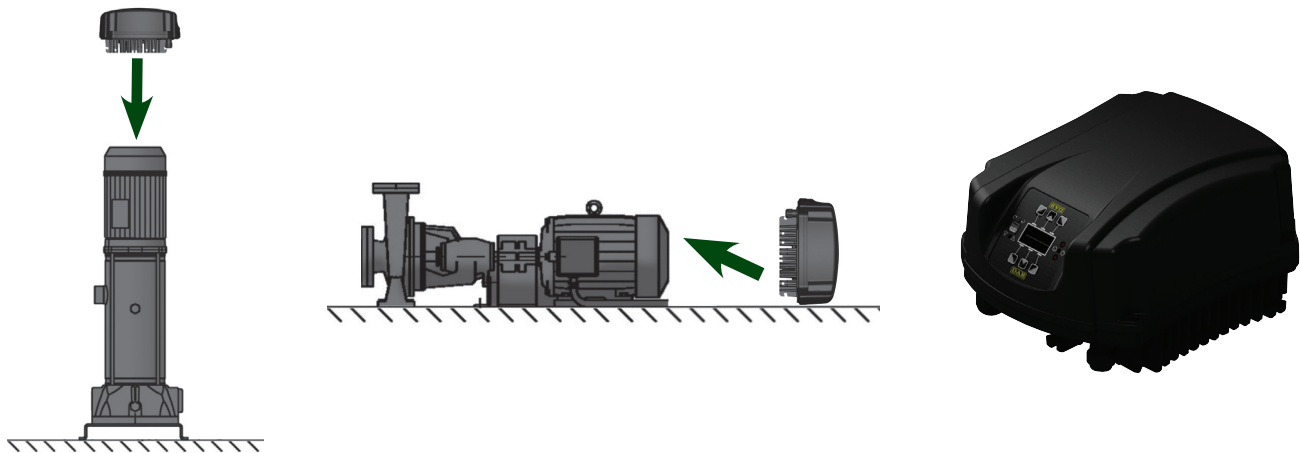
The rotation speed is kept at a constant rpm. The rotation speed can be set between a minimum value and the rated frequency of the circulation pump (e.g. between 15 Hz and 50 Hz). This mode can be set using the control panel on the cover of the MCE.



Constant Curve Control with Remote Analogue Signal

The rotation speed is kept at a constant number of rpm proportional to the voltage of the remote analogue signal. The rotation speed varies on a linear scale between the rated frequency of the pump when $V_{in} = 10V$ and the minimum frequency when $V_{in} = 0V$. This mode can be set using the control panel on the cover of the MCE.

1 Hydraulic diagram



The MCE is installed on the motor base. The inverter can operate both vertically and horizontally. 2 kits are available for assembly on the motor:

Tie-rods:

These are connected to the MCE dissipator and fan cover. They require a solid fan cover able to withstand the weight of the inverter, i.e. secured by means of bolts or screws.

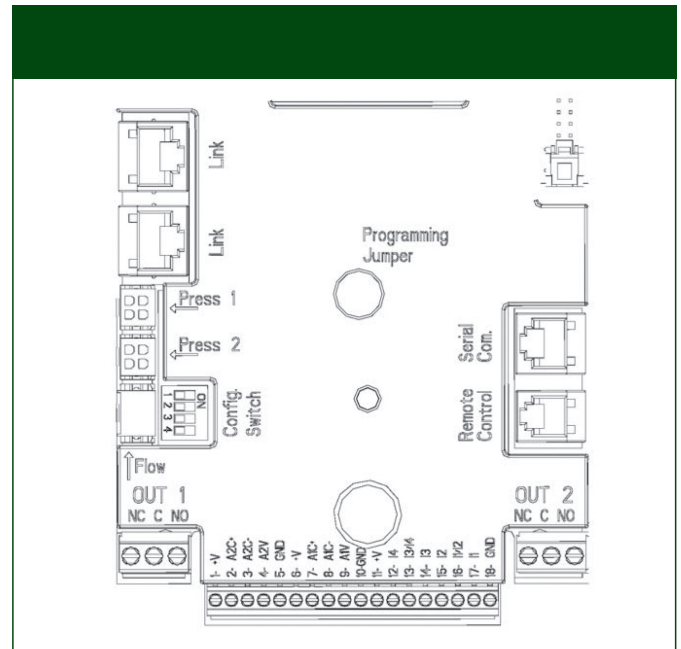
Fan cover kit:

The fan cover kit is used in all situations where the fan cover is not sufficiently solid or strong enough to withstand the weight of the inverter.

TWIN OPERATION

Groups of up to 2 pumps can be created. To do this, the pumps must be hydraulically connected to the same output and inlet manifolds (naturally, this is not necessary for twin circulation pumps).

The 2 MCE/C inverters also have to be connected using the special interconnection cable, connecting both inverters to one of the 2 connectors marked Link. For the twin system to operate correctly, all the external connections of the input terminal board must be parallel connected between the 2 MCE/C units, with the numbers of the individual pins corresponding (e.g. pin 17 of MCE-22/C-1 to pin 17 of MCE-22/C-2 and so on).



Connection of the power line

Single-phase electric connection diagram (up to MCE-22/C)

The connection between the MCE-22/C and the single-phase power supply line must be made with a 3-wire cable (live + neutral + ground). The input terminals are marked LINE LN with an arrow pointing into the terminals. (see Figure 1)

The input and output cables must be large enough to allow the cable clamps to grip them effectively, while the maximum permitted gauge on the terminals is 4 mm². The electric pump supply current is generally specified on the motor dataplate. Generally, the maximum power supply current of the MCE-22/C can be estimated as twice the maximum current absorption of the pump. Although the MCE-22/C has its own internal protection devices, an overload cutout of suitable rating should also be installed.

Three-phase connection diagram (MCE-30/C and MCE-55/C)

The connection between the MCE-30/C and MCE-55/C and the three-phase power supply line must be made with a 4-wire cable (3 phases + ground). The input terminals are marked LINE RST with an arrow pointing into the terminals. (see Figure 2)

The maximum permitted wire gauge of the input and output terminals is 6 mm². The input and output cable outside diameter which will allow the cable clamps to secure them correctly varies from a minimum of 11 mm² up to a maximum of 17 mm². The electric pump supply current is generally specified on the motor dataplate. Generally, the power supply current of the MCE-55/C can be estimated as 1/8 greater than the maximum current absorption of the pump (with a safety margin). Although the MCE-55/C has its own internal protection devices, an overload cutout of suitable rating should also be installed.

Three-phase connection diagram (MCE-110/C and MCE 150/C)

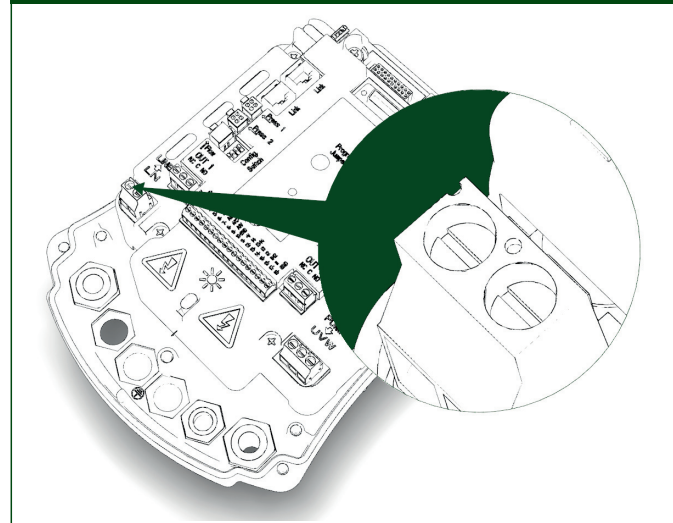
The connection between the MCE-110/C and MCE-150/C and the three-phase power supply line must be made with a 4-wire cable (3 phases + ground). The input terminals are marked LINE RST with an arrow pointing into the terminals. (see Figure 3)

The input and output cables must have gauge of at least 6 mm² to allow the cable clamps to grip them effectively, while the maximum permitted gauge on the terminals is 16 mm².

Generally, the power supply current of the MCE-110/C and MCE-150/C can be estimated as 1/8 greater than the maximum current absorption of the pump (with a safety margin). Although the MCE-110/C and MCE-150/C have their own internal protection devices, an overload cutout of suitable rating should also be installed.

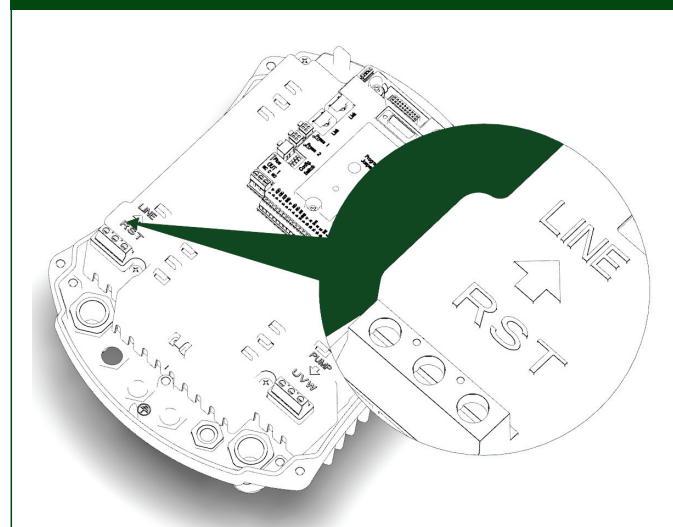
MCE/C 11 – MCE/C 15 – MCE/C 22

figure 1



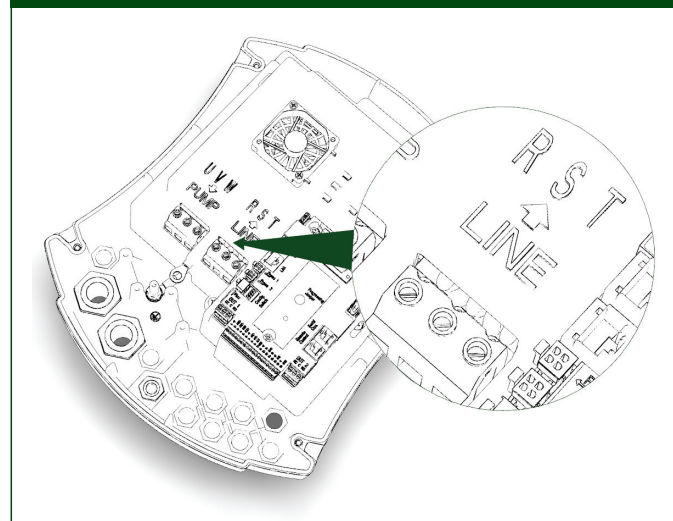
MCE/C 30 - MCE/C 30

figure 2



MCE/C 110 - MCE/C 150

figure 3



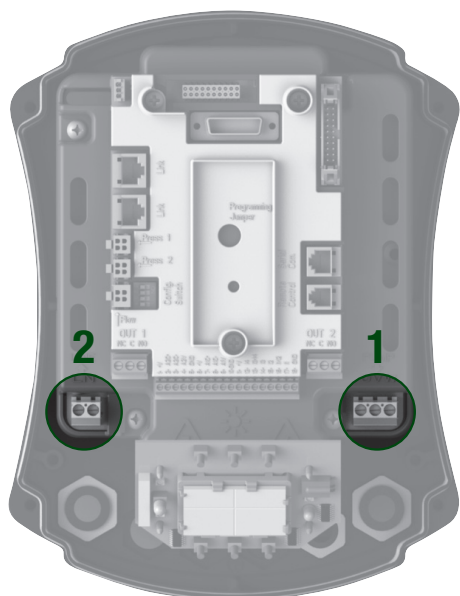
QUICK START GUIDE

PUMP AND POWER SUPPLY CONNECTION



MCE/P 11 – MCE/P 15 – MCE/P 22

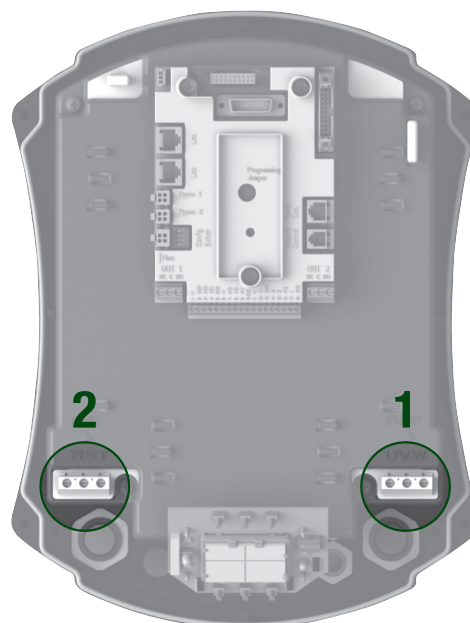
Installation



- 1 Connect the power supply to the pump
- 2 Connect electrically the inverter

MCE/P 30 – MCE/P 55

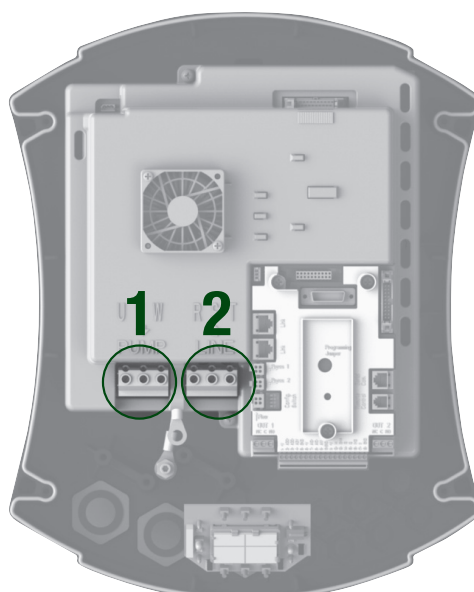
Installation



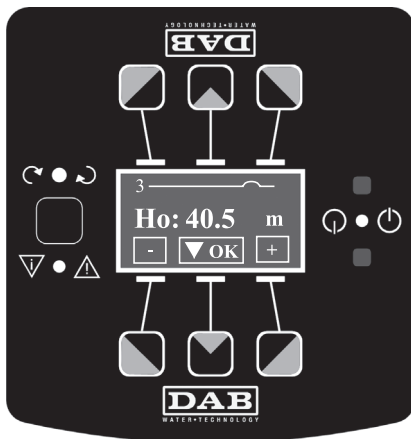
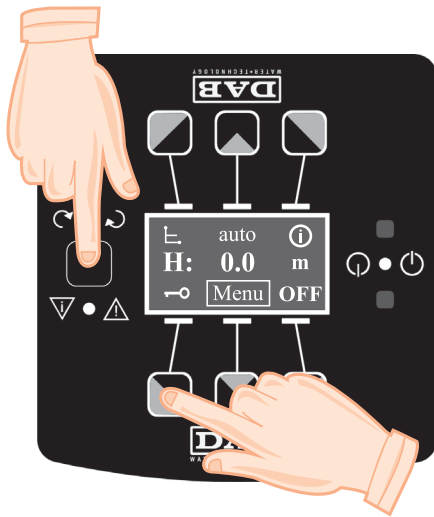
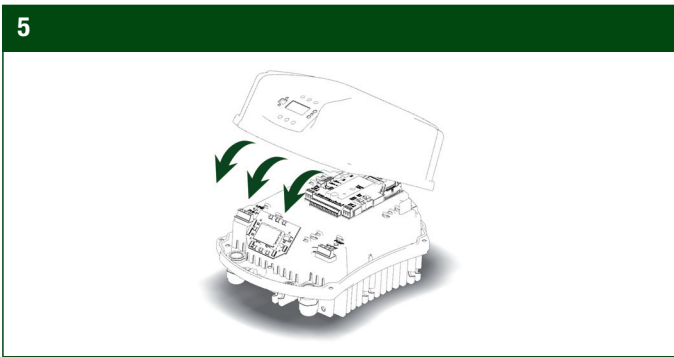
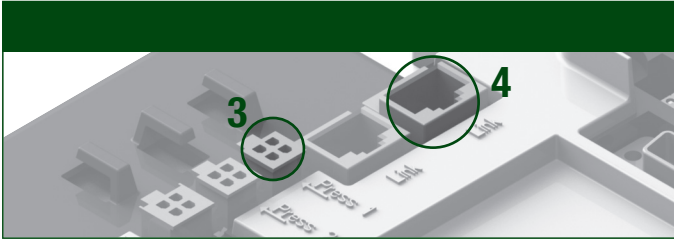
- 1 Connect the power supply to the pump
- 2 Connect electrically the inverter

MCE/P 110 – MCE/P 150

Installation



- 1 Connect the power supply to the pump
- 2 Connect electrically the inverter



3. Sensor lead connection

The pressure sensor lead must be connected to press1

4. Communication lead connection

In a twin system, connect the communication lead between the two inverters

5. MCE/C Configuration

Close the cover and power up the inverter, the display will show

6. Inverter unlocking

Press and hold the key button and side button for 5 seconds until the key symbol disappears (See Fig. 6)



Button functions

The central button enables the user to scroll through the parameters Buttons + and – are used to input the required value. The value is saved if the OK button is pressed for 3 seconds

7. Installation Menu

Press and hold the central button for 5 seconds until the product name is displayed.

8. Installation Menu

Briefly press the central button to display the rated frequency of the pump, **Fn**, and modify if necessary

9. Current control protection settings

In: Rated current of pump.
Set the pump protection current according to the data of the electric pump

10. Setting the direction of rotation

Press + and - to set **Rt** (direction of pump rotation).

11. Optional parameters

if necessary, set: Minimum frequency, maximum frequency, **Rpm**

12. Setting the type of pressure sensor

Select the type of differential pressure sensor installed

13. Set the maximum pump pressure head

14. Setting the carrier frequency

If necessary, set the carrier frequency value.



If necessary, return to the installation menu from the home page and press and hold the central button for 5 seconds.

INPUT AND OUTPUT ELECTRICAL CONNECTIONS



The MCE/C has 2 digital inputs, one analogue input and 2 digital outputs, allowing a number of interface solutions to be created with more complex installations.

Digital Inputs

The screen-printed key to the digital inputs is provided on the base of the 18 pin terminal board:

- 11 - V+
- 15 - I2
- 16 - I1/I2
- 17 - I1
- 18 - GND

The inputs can be excited in both direct and alternating current. The electrical characteristics of the inputs are illustrated below.

| ELECTRICAL CHARACTERISTICS OF INPUTS | | |
|--|---------------|------------------|
| | DC Inputs [V] | AC Inputs [Vrms] |
| Minimum excitation voltage [V] | 8 | 6 |
| Maximum shut-off voltage [V] | 2 | 1,5 |
| Maximum permissible voltage [V] | 36 | 36 |
| Current absorption at 12V [mA] | 3,3 | 3,3 |
| Max. permitted cable cross-section [mm ²] | 2,13 | |
| N.B. The inputs can be controlled with any polarity (positive or negative in relation to their own ground) | | |

| R1 | R2 | SYSTEM STATUS |
|-------|-------|---|
| Open | Open | Pump stopped OFF |
| Open | Close | Pump stopped OFF |
| Close | Open | Pump running with set-point set by user - AU |
| Close | Close | Pump running with reduced set-point - ECONOMY |

Outputs:

The output connections illustrated below refer to the two 3-pin terminal boards marked OUT1 and OUT2, also marked with the terminal contact type (NC = Normally Closed, C = Common, NO = Normally Open).

| OUTPUT CONTACT CHARACTERISTICS | |
|---|---|
| Contact type | NO, NC |
| Max. rated voltage [V] | 250 |
| Max. rated current [A] | 5 If resistive load / 2,5 If inductive load |
| Max. permitted cable cross-section [mm ²] | 3,80 |

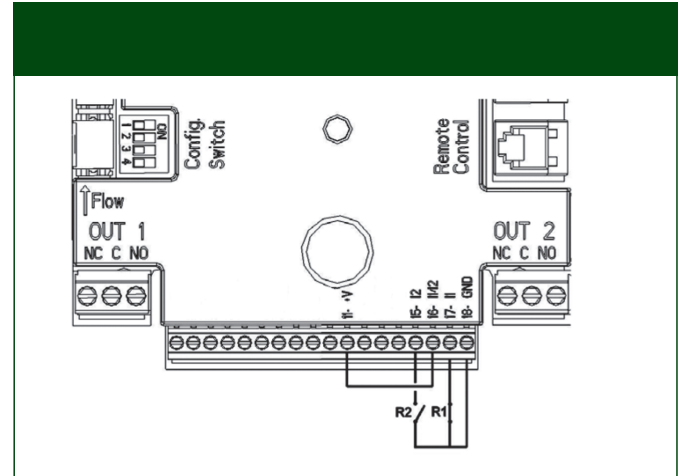
| FUNCTIONS ASSOCIATED TO THE OUTPUTS | |
|-------------------------------------|------------------------------|
| OUT1 | Alarms / No Alarms in system |
| OUT2 | Pump running / Pump stopped |

Analogue Input for Constant Curve Control Mode with Remote Analogue Signal

The screen-printed marking of the 0-10V analogue input is provided on the base of the 18 pin terminal board:

- A1V (pin 9): Positive pole
- GND (pin 10): Negative pole

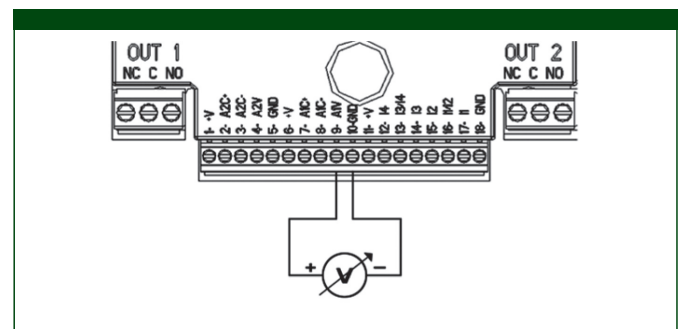
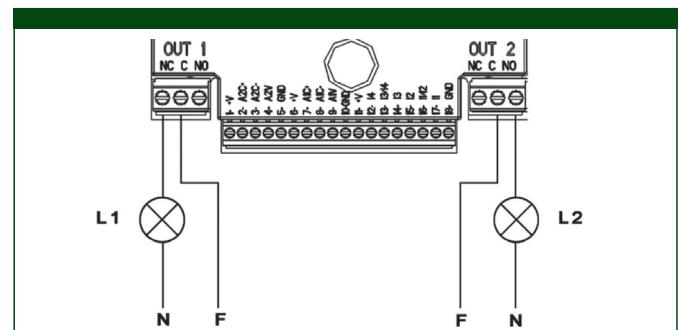
The function associated to the 0-10V analogue input is regulation of the pump rpm in proportion to the voltage on the 0-10V input itself.



If a voltage is available and not a contact, it can still be used to control the inputs: do not use the +V and GND terminals and connect the voltage source to the input required complying with the characteristics detailed above.

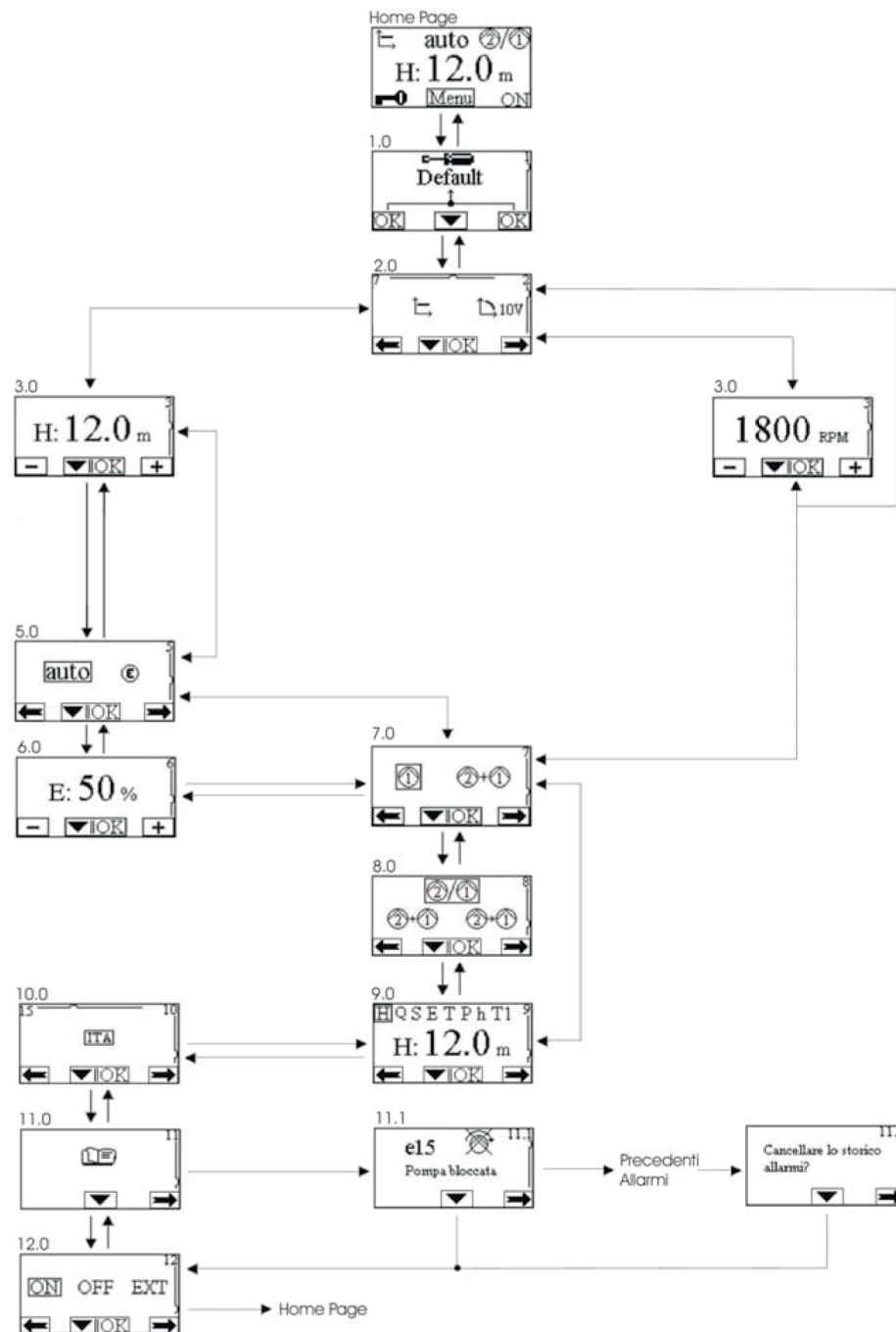
| FUNCTIONS ASSOCIATED TO THE DIGITAL INPUTS | |
|--|---|
| L1 | Start/Stop: If input 1 is activated from the control panel, pump start and stop can be remote controlled. |
| L2 | Economy: If input 2 is activated from the control panel, the set-point reduction function can be remote controlled. |

In the example shown, light L1 comes on when there is an alarm in the system and goes out when no malfunctions of any kind are detected, while light L2 comes on when the pump is running and goes out when it is stopped.



MCE/C MENU CONFIGURATION












The settings are made by passing from page to page in the circulator setup menu.



DESCRIPTION OF PARAMETERS WHICH CAN BE DISPLAYED

| Symbol | Description |
|--------|-----------------------|
| HSEPh | Display of parameters |
| H | Head in m |
| S | Speed (rpm) |
| E | 0-10 V analogue input |
| P | Power in kW |
| h | Operating hours |

TYPES OF ALARMS AND HOW TO DEAL WITH THEM

| Alarm code | Alarm symbol | Alarm description |
|--------------------|---|--------------------------|
| e0 - e16; e21 |  | Internal Error |
| e17 - e19 |  | Short circuit |
| e20 |  | Voltage Error |
| e22 - e30 |  | Voltage Error |
| e31 |  | Protocol Error |
| e32 - e35 |  | Overheating |
| e37 |  | Low voltage |
| e38 |  | High voltage |
| e39 - e40 |  | Overcurrent |
| e43; e44; e45; e54 |  | Pressure sensor |
| e46 |  | Pump Disconnected |

Errors and how to deal with them

| Display indication | Description | Reset |
|--------------------|--|--|
| E0 - E16 | Internal Error | - Switch off power to MCE- Wait 5 minutes then restore power to the MCE.- If the error persists, replace the MCE. |
| E37 | Mains voltage too low (LP) | Switch off power to MCE - Wait 5 minutes then restore power to the MCE. - Check that the mains system voltage is correct; if necessary, restore it to the device's rated level. |
| E38 | Mains voltage too high (HP) | -- Switch off power to MCE - Wait 5 minutes then restore power to the MCE. - Check that the mains system voltage is correct; if necessary, restore it to the device's rated level. |
| E32-E35 | Overheating of key electronic parts | - Switch off power to MCE - Wait 5 minutes then remove the MCE from the pump and clean the motor casing. - Clean the heat sink |
| E43-E45; E54 | No signal from sensor | - Check the sensor connection - If the sensor has failed, replace it. |
| E39-E40 | Overload cutout tripped | - Check that the circulation pump turns freely. - Check that the level of antifreeze does not exceed the maximum level of 30% |
| E21-E30 | Voltage Error | - Switch off power to MCE. - Wait 5 minutes then restore power to the MCE. - Check that the mains system voltage is correct; if necessary, restore it to the device's rated level. |
| E31 | Twin connection failure | - Inspect the twin connection cable for damage. - Check that both circulation pumps can be supplied with power. |



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